Manipal Institute of Technology, Manipal

Reg. No.

(A Constituent Institute of Manipal University)

VI SEMESTER B.TECH (ELECTRICAL & ELECTRONICS ENGINEERING)

MAKEUP EXAMINATIONS, JULY 2016

SUBJECT: SOFT COMPUTING [ELE 328]

REVISED CREDIT SYSTEM

04, July 2016

Time: 3 Hours

प्रज्ञानं ब्रह्म

INSPIRED BY LIFE

Instructions to Candidates:

- ✤ Answer any **FIVE** full the questions.
- Missing data may be suitable assumed.
- 1A. Write the expressions for the following: (i) Yager compliment (ii) Dubois-Prade S-norm
- 1B. Sketch the membership functions described and mark the constants used by the following expressions:

(i)
$$\mu$$
 (i) μ (ii) μ (ii) μ (ii) μ (iii) μ (iv) $h \leq x \leq b$

$$\begin{cases} 0 & x \leq a \\ \frac{x-a}{b-a} & a \leq x \leq b \\ 1 & b \leq x \leq c \\ \frac{d-x}{d-c} & c \leq x \leq d \\ 0 & x \geq d \end{cases}$$
(04)

1C. An FIS has a rule "IF Flux is large THEN speed is low". Consider fuzzy sets "large" and "NOT large" defined in Flux: {x1, x2, x3} and "low" defined in speed: {y1, y2} as shown below:

$$\operatorname{large} = \left\{ \frac{0.5}{x_1} + \frac{1}{x_2} + \frac{0.6}{x_3} \right\}; \quad \operatorname{low} = \left\{ \frac{1}{y_1} + \frac{0.4}{y_2} \right\}; \quad \operatorname{NOT} \operatorname{large} = \left\{ \frac{0.6}{x_1} + \frac{0.9}{x_2} + \frac{0.7}{x_3} \right\};$$

Determine the fuzzy set "NOT low" using

- (i) Zadeh implication and
- (ii) Dienes-Rescher implication.
- 2A. A neural network has one layer of two neurons. The available information of the network are W = $\begin{bmatrix} 2 & -1 \\ 0.5 & 0.75 \end{bmatrix}$, Bias = $\begin{bmatrix} -0.5 \\ -1 \end{bmatrix}$ and O = $\begin{bmatrix} 0.28 & -0.73 \\ -1 \end{bmatrix}$. Biasing input = -1. The activation function is bipolar continuous with λ = 1.25. Determine

(04) the input matrix X and sketch the neural network.



(02)

MAX. MARKS: 50

(04)

2B. Consider the fuzzy sets

$$A = \left\{ \frac{0.4}{1} + \frac{0.7}{2} + \frac{1}{3} + \frac{0.8}{4} \right\} \text{ and } B = \left\{ \frac{0.2}{1} + \frac{0.6}{2} + \frac{0.9}{3} + \frac{0.7}{4} \right\}, \text{ prove that } \overline{A \cup B} = \overline{A} \cap \overline{B}$$
 (02)

2C. The membership function of a fuzzy set Y is defined as follows in a universe of discourse U:[0:4]

$$\mu \not \bigcirc = \begin{cases} 0.25 * y^2 & 0 \le y \le 2\\ 1 & 2 \le y \le 3\\ 4 - y & 3 \le y \le 4 \end{cases}$$

Sketch the membership function and determine the crisp value Y* using centroid defuzzification method. (04)

- 3. A 20 MVA alternator delivers 1.0 pu power to an infinite bus over a double circuit transmission line. The inertia constant $M = 2.8 \times 10^{-4} \sec^2$ /electrical degree. When a symmetrical fault occurs on one of the transmission line the power output is given by 0.88*Sin δ . A braking resistor is used to improve transient stability. A fuzzy inference system is to be designed to determine the power dissipated P_R in the braking resistor with inputs as rotor speed (d δ /dt) and accelerating power (P_a) Given the initial conditions of power angle $\delta_0 = 21.64^0$ and (d δ /dt) = 75⁰/sec at t = t₀, determine the braking resistance required in first swing. The required membership functions are shown in Fig. Q3. Use last of maximum defuzzification. (10)
- 4A. Design a bipolar discrete neural model such that the input pattern lies in the shaded region shown in Fig. Q4A.
- 4B. A₁ and A₂ are fuzzy sets defined as $A_1 = \left[\frac{0.5}{-1} + \frac{0.1}{0} + \frac{0.9}{1}\right]$ and $A_2 = \left[\frac{0.4}{-2} + \frac{1}{2}\right]$. Using extension principle derive $f (A_1, A_2)$ given $f (A_2, Y) = x^2 + x^* y$ (03)
- 4C. The initial weight matrix of a neural network is $W^{\Phi} = \begin{bmatrix} -1 & 0 & 0.5 \end{bmatrix}^{\overline{T}}$. The set of input training vectors and desired responses are given below:

$$X_1 = \begin{bmatrix} -2 & 0 & -1^{\overline{t}}; \\ -2 & 0 & -1^{\overline{t}}; \end{bmatrix}$$
 $X_2 = \begin{bmatrix} 1.5 & -0.5 & -1^{\overline{t}}; \\ -1, \\ -1, \\ -1; \end{bmatrix}$ $d_2 = -1;$

Assuming learning constant c = 0.4 and $\lambda = 1$ for bipolar sigmoidal activation function, determine the modified weights at the end of one cycle using delta learning rule.

5A. A neural network has two neurons in its hidden layer with biasing synaptic weight of -0.5 for each neuron connected to a single input X. The output layer has five neurons with biasing synaptic weight of -1 for each neuron. The biasing signal for all neurons is -1. The activation function for hidden layer is unipolar sigmoidal while the output neurons have their activation function defined by f(net)=net. Hidden layer weights are Y = $[0.5 \ 0.8]^t$. Output layer weights are $W = \begin{bmatrix} 1 & 0.7 & 0.5 & 0.6 & 0.91 \\ 0.5 & 1 & 1 & 0.9 & 1 \end{bmatrix}$

Sketch the network described as above.

If the desired output $0 = [6 \ 7 \ 8 \ 9 \ 10]^t$ for an input X = 4, determine the output error matrix. (06)

(03)

(04)

- 5B. Using genetic algorithm, find the maximum value of the given function $y = e^{-(x-3)^2}$ where 1 < x < 5 using 5 bit binary string. The initial population given are $[1\ 0\ 0\ 0\ 1]$, $[0\ 0\ 1\ 1\ 0]$, $[1\ 0\ 1\ 0\ 0]$, $[0\ 1\ 0\ 1\ 1]$. (04)
- 6A. Design a neural network to perform the following classification:

Class A : $x_1 = (0.5, 1)$, $x_2 = (2, 1)$ and $d_1 = -1$ Class B : $x_3 = (-1, 1)$, $x_4 = (-2, 1)$ and $d_2 = 1$

The learning constant is 0.5 and initial weight vector is $[2, 1.5]^t$. Draw the locus of weight vector in W_1/W_2 plane.

6B. It is required to store two patterns $S_1 = [1 - 1 1 - 1]^t$ and $S_2 = [-1 1 - 1 1]^t$ in an associative memory using Hopfield network. Obtain the suitable weight matrix. For asynchronous mode of bit transfer, draw the state transition diagram when the input for the network is $[1 1 1 1]^t$. Calculate the energy level for the initial and final state in the transition diagram.



Fig. Q 3



Fig. Q 4A

(05)

(05)