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MANIPAL INSTITUTE OF TECHNOLOGY
Manipal University
THIRD SEMESTER B.TECH (E & C) DEGREE END SEMESTER
EXAMINATION - NOV/DEC 2016
SUBJECT: SIGNALS AND SYSTEMS (ECE -2104)

TIME: 3 HOURS

MAX. MARKS: 50

Instructions to candidates

- Answer **ALL** questions.
- Missing data may be suitably assumed.

- 1A. Distinguish between power and energy signals. Categorize the following as power or energy signals and find the energy or power of the signal. (i) $x[n] = \left(\frac{1}{2}\right)^n u[n]$ (ii) $x(t) = \cos^2(\omega_0 t)$. Also sketch the even and odd components of $x[n]$ and $x(t)$.
- 1B. Determine whether the following systems described by the input-output relation are time-invariant or not?
- (i) $y(t) = \log\{x(t)\}$ (ii) $y[n] = x[n]\cos(\omega_0 n)$
- 1C. Determine whether the signal $x(t) = 2\cos(t) + 3\cos(t/3)$ is periodic or not. If periodic, calculate its period.
- (5+3+2)
- 2A. Suppose that the input $x(t)$ and impulse response $h(t)$ of a LTI system is given by $x(t) = \begin{cases} 2, & -2 \leq t \leq 2 \\ 0, & \text{elsewhere} \end{cases}$ and $h(t) = \begin{cases} 4, & 0 \leq t \leq 2 \\ 0, & \text{elsewhere} \end{cases}$ respectively. Using convolution, evaluate the output $y(t)$ of the LTI system and also sketch the output $y(t)$.
- 2B. A certain LTI system has impulse response, $h[n] = \left(\frac{3}{4}\right)^n u[n]$. Determine the step response of the system using time-domain convolution.
- 2C. Obtain the direct form-I and direct form-II implementations for the LTI system defined by, $2y[n] + 3y[n-1] - y[n-2] - 2x[n-1] + 4x[n-2] = 0$.
- (5+3+2)
- 3A. The impulse response of a continuous time system is given by, $h(t) = \cos(5\pi t) \frac{\sin(\pi t)}{\pi t}$. Find the output to the input $x(t) = 2 + \cos(\pi t) - 2\sin\left(\frac{5}{2}\pi t\right) - 2\cos(6\pi t)$.
- 3B. Determine the DTFT of the signal, $x[n] = n\left(\frac{1}{2}\right)^n u[n-3]$.

- 3C. Using properties of FT determine the signal $x(t)$ if its spectrum is $X(j\omega) = \frac{1}{1+\omega^2}$ (5+3+2)

- 4A. Consider the system shown in Figure Q4A with input signal $x(t) = \cos(\pi t)$. Sketch $X_p(j\omega)$ for (i) $T=1/3$ and (ii) $T=1$.

- 4B. Determine an impulse response of discrete-time causal inverse system to eliminate the effect of echo received along with the signal. The echo is one unit time delayed with strength half of the input signal.

- 4C. Determine the difference equation of the system that has DTFT, $H(e^{j\Omega}) = \frac{1+e^{-j\Omega}}{3+e^{-j2\Omega}}$. (5+3+2)

- 5A. Determine the time domain signal corresponding to Z-transfer function,

$$H(z) = \frac{1 + \frac{7}{6}z^{-1}}{\left(1 - \frac{1}{2}z^{-1}\right)\left(1 + \frac{1}{3}z^{-1}\right)} \quad \text{if, (i) } |z| > \frac{1}{2} \quad \text{ii) } |z| < \frac{1}{3} \quad \text{iii) } \frac{1}{3} < |z| < \frac{1}{2}.$$

- 5B. Determine bilateral Z-transform of the rectangular window sequence $x[n] = \begin{cases} 1; & 0 \leq n \leq 7 \\ 0; & \text{elsewhere} \end{cases}$

Plot the poles and zeroes in z-plane and indicate ROC.

- 5C. Determine the bilateral Laplace Transform and ROC for the signal, $x(t) = \cos(3t)u(t)$. (5+3+2)

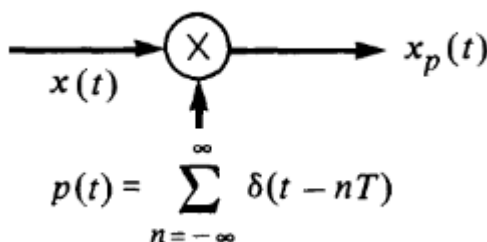


Figure Q4A

