Reg. No.

(A Constituent Institute of Manipal University)

Manipal Institute of Technology, Manipal

I SEMESTER M.TECH (INDUSTRIAL AUTOMATION AND ROBOTICS, **MECHATRONICS ENGINEERING) END SEMESTER EXAMINATIONS,**

DEC 2015 – JAN 2016

SUBJECT: SIGNAL PROCESSING AND APPLICATIONS [MTE 509]

Time: 3 Hours

Instructions to Candidates:

- Answer ANY FIVE FULL questions.
- Transform Tables to be provided
- ✤ Missing data may be suitably assumed.
- Design a digital IIR filter for the following magnitude response. 1A.



- 2A. Explain briefly any application of signal processing with neat block diagrams. (6m)
- 2B. Realize the digital filter given H(s) = $\frac{z + 5z + 5}{z^3 + 6z^2 + 11z + 6}$ (4m)
- 3A. Categorize whether the system $y(n) = nx(n) + \frac{1}{x(n-1)}$ as linear, non-linear, static-dynamic, (4m) time variant-invariant, causal-noncausal.
- Find the output if $x(n) = \{[1], 2, -1, 1\}$ and $h(n) = \{1, [0], 1, 1\}$ 3B. (2m)





MAX. MARKS: 50

3C. A packaging industry is doing the labelling using a plunger as shown below. Find the transfer function in z domain and the response of the system in discrete domain.



- **4A.** State dirchlets conditions. What is the significance of dirchlet's conditions in signals. (3m)
- **4B.** Find the z transform of the following $f(t) = \left(\frac{1}{3}\right)^n u(n)$. Also mention the region of convergence. (5m)
 - i. f(n) ii. $a^n f(n)$ iii. f(-n) iv. nf(n)
- **4C.** $x(n) = \{4,2,-1,[1],3,2,1,5\}$ represent the sequence as sum of elementary functions. (2m)
- **5A.** Design an FIR digital filter with $n = \{0,1,2,3\}$ whose magnitude response is $H(e^{jw}) = e^{-3jw}$ for $-\frac{3\pi}{2} \le w \le \frac{3\pi}{2}$, and zero elsewhere. Also the weighting factor w(n) = 1 (6m) for all n.
- **5B.** Find y(n) = x(n)*h(n) in z domain if $x(n) = 2^n u(n-5)$ and $h(n) = \{1, [0], 1, 1, \}$. Also mention the region of convergence of y(n). (4m)
- **6A.** Design a third order digital butterworth filter that pass the frequency signals beyond (10m) analog frequency of $\Omega c = 2.5$ rad/sec.