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MANIPAL INSTITUTE OF TECHNOLOGY

MANIPAL

A Constituent Institution of Manipal University

I SEMESTER M.TECH. (COMPUTER AIDED ANALYSIS AND DESIGN) END SEMESTER EXAMINATIONS, NOV/DEC 2016

SUBJECT: ADVANCED MECHANICAL VIBRATIONS [MME 5102]

REVISED CREDIT SYSTEM
(26/11/2016)

Time: 3 Hours

MAX. MARKS: 50

Instructions to Candidates:

- ❖ Answer **ALL** the questions.
- ❖ Missing data may be suitable assumed.

- 1A.** Distinguish between
i) Vibration Isolation and Vibration Absorption
ii) Principle mode and Normal mode of Vibration
iii) Frequency Response and Time Response
iv) Linear and Nonlinear systems. **02**
- 1B.** A horizontal shaft is supported between bearings (simply supported). At the centre of the shaft, a disc of mass “m” is mounted. The lateral stiffness of the shaft is “k”. Due to manufacturing inequalities, the centre of gravity is shifted by a distance “e” from the geometric centre. The lubrication at the bearings provides a damping of “c”. Derive the expression for the lateral deflection of the shaft in terms of eccentricity “e” and angular velocity ‘ ω ’. **04**
- 1C.** Determine the natural frequency of a spring mass system, considering the mass of the spring. **04**
- 2A.** An automobile chassis has a mass of 600 kg and the total spring constant of its suspension system is 58 kN/m. If the profile of a stretch of a road which it travels at a speed of 60 kmph may be approximated as a sinusoidal profile (rumblers) with peak to peak distance of 100 mm and a wave length of 1.0 m determine the steady state amplitude as well as amplitude corresponding to resonance condition. Assume a damping factor of 0.05. **03**
- 2B.** What is the need for a dynamic vibration absorber? Explain its working principle with a neat sketch. **04**
- 2C.** Give a brief outline of the Lanczos procedure for Eigen Value Problems. **03**
- 3A.** Explain the design principles of Accelerometer and Vibrometer. **03**

- 3B.** Describe the Lindstedt's perturbation method for solution of equations describing Nonlinear vibrations. **04**
- 3C.** With a neat sketch explain what is meant by a 'limit cycle' **03**
- 4A.** Explain Sub harmonic oscillations of Nonlinear systems with a neat sketch. **03**
- 4B.** Explain time and frequency domain analysis with respect to machine condition monitoring **03**
- 4C.** Derive the free vibration equation for longitudinal vibrations of bars and obtain its solution. **04**
- 5A.** Using Holzer's method, determine the length 'L' of the shaft shown in figure Q5A, given that its fundamental frequency is 150 rad/sec. Use $K_t = 2 \times 10^6$ Nm/rad; $J_1 = J_2 = 10 \text{ kgm}^2$; $J_3 = J_4 = 30 \text{ kg-m}^2$ $G = 80 \text{ GPa}$; shaft diameter = 10 cm. **04**
- 5B.** With a neat sketch explain the working of a Linear Variable Differential Transformer (LVDT). **04**
- 5C.** Define the following with respect to random processes
1. Standard Deviation
 2. Autocorrelation
 3. Spectral Density
 4. Covariance
- 02**

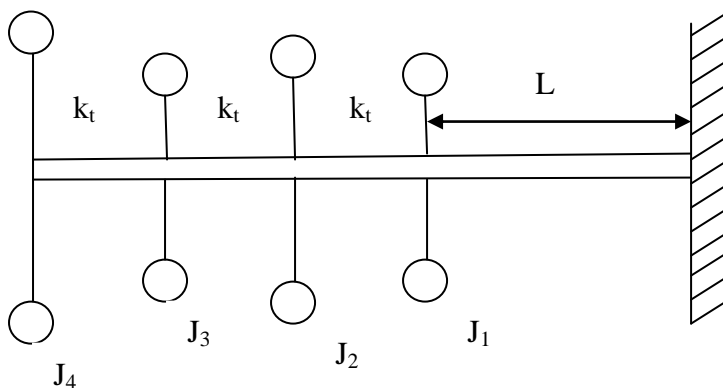


Figure Q 5A