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MANIPAL INSTITUTE OF TECHNOLOGY
MANIPAL
A Constituent Institution of Manipal University

FIFTH SEMESTER B.TECH. (INSTRUMENTATION AND CONTROL ENGG.)

END SEMESTER EXAMINATIONS, DEC 2016/JAN 2017

SUBJECT: MICROPROCESSORS & MICROCONTROLLERS [ICE 3104]

Time: 3 Hours

MAX. MARKS: 50

Instructions to Candidates:

- ❖ Answer **ALL** the questions.
- ❖ Missing data may be suitably assumed.

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| 1A. | With basic block diagram, explain the architecture of 8051 microcontroller. | 4 |
| 1B. | Draw the diagram to connect 8k RAM and 16k ROM externally to 8051 and explain its working with timing diagram. | 4 |
| 1C. | Explain the different criteria's for selecting microcontroller. | 2 |
| 2A. | Mention any three addressing modes of 8051 and explain each with an example. | 3 |
| 2B. | Write an ALP using 8051 mnemonics to generate a time delay using nested loop (Assume the inner and outer loop count as 100). Also calculate the generated delay. | 4 |
| 2C. | Using register addressing mode and direct addressing mode swap the content of registers R5 and R6 in register bank 0. | 3 |
| 3A. | Explain the function of each bit in PSW and TMOD. | 4 |
| 3B. | What are interrupts and interrupt subroutines? Explain 8051 interrupt structure. | 4 |
| 3C. | Explain the significance of SBUF in 8051. | 2 |
| 4A. | List any six features of LPC2148 and explain the THUMB architecture with relevant diagram. | 6 |
| 4B. | With respect to ARM, explain i) AMBA ii) IO0SET and IO0CLR. | 4 |
| 5A. | Using LPC 2148 write a program to rotate the stepper motor by 135° clockwise direction when switch S2 is pressed. Also show its keyboard and stepper motor interface to LPC 2148. | 6 |
| 5B. | With suitable example, explain the load and store instructions in ARM. | 4 |