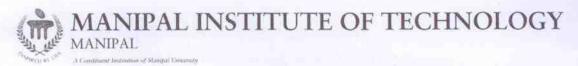
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## VII SEMESTER B.TECH. (AUTOMOBILE ENGINEERING) END SEMESTER EXAMINATIONS, NOV/DEC 2016

SUBJECT: COMPUTER INTEGRATED MANUFACTURING [AAE 453]

## REVISED CREDIT SYSTEM (02/12/2016)

Time: 3 Hours MAX. MARKS: 50

## Instructions to Candidates:

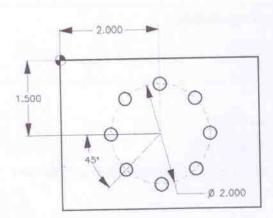
- Answer ANY FIVE FULL questions.
- . Draw Sketch's using PENCIL only.

**AAE 453** 

1A.	List the steps involved in the program planning.	(03)
1B.	Discuss automated storage and retrieval systems.	(03)
1C.	Classify the CNC machine tools based on machining centers & explain any two.	(04)
2A.	Explain the axial grooving instruction format with a sample program.	(03)
2B.	Contrast the differences between Uni-polar and Bi-polar Stepper motors.	(03)
2C.	Discuss the different components related to the CNC machine tools.	(04)
3A.	Sketch and explain linear and rotary type of encoders used in CNC machines.	(05)
3B.	Explain the benefits of using cellular manufacturing.	(02)
3C.	Write CNC program for figure 1 using G70 Bolt Hole Circle G-code to drill 8 holes evenly spaced in a circle.	(03)
4A.	Sketch and explain the working principle of SCARA robot with its application.	(03)
4B.	Sketch and explain the following mechanical end effector configurations	(04)
	i. Rack and Gear type of actuation	
	ii. cam type of Actuation	
4C.	Explain the different types of sensors used in robots.	(03)
5A.	Define tool vector input & share its benefits.	(02)
5B.	Discuss different types of probes used in CMM.	(03)

Page 1 of 2

- 5C. Define Group technology. Explain ways and means to identify part families. (05) Explain how parts classification and coding is done in group technology?
- 6A. Write a part program for the figure.2 shown below considering cut per pass as (04) 0.5mm.
- 6B. Solve table 1 using rank order clustering algorithm. (04)
- 6C. List the components of the machine vision system. (02)



Machines	1	2	3	4	5	6	7	8	9	10
M1	1	1	1	1	1		1	1	1	E
M2		1	1	1					1	1
M3	1				1	1	1			
M4		1	1	1				1	1	1
M5	1	1.	1	1	1	1	1	1		

Table.1

Fig 1 (consider hole size as 0.1" & depth as 0.5")

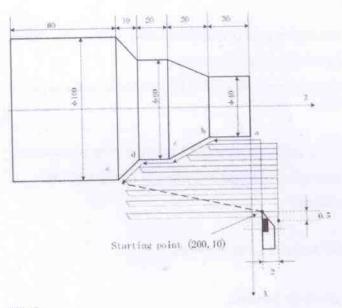


Fig 2