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**MANIPAL INSTITUTE OF TECHNOLOGY**  
**MANIPAL**

*A Constituent Institution of Manipal University*

**VII SEMESTER B.TECH. (AUTOMOBILE ENGINEERING)**

**END SEMESTER EXAMINATIONS, DEC 2016-JAN 2017**

**SUBJECT: COMPUTER INTEGRATED MANUFACTURING [AAE 453]**

**REVISED CREDIT SYSTEM  
 (04/01/2017)**

Time: 3 Hours

MAX. MARKS: 50

**Instructions to Candidates:**

- ❖ Answer **ANY FIVE FULL** questions.
- ❖ Draw Sketch's using **PENCIL** only.

- 1A.** Write a note on conveyor type of material handling systems. **(03)**
- 1B.** Discuss the concept of CAPP. **(03)**
- 1C.** Sketch and explain the working of DNC machines. **(04)**
  
- 2A.** Explain the threading cycle instruction format with a sample program. **(03)**
- 2B.** List the advantages and disadvantages of stepper motor. **(03)**
- 2C.** Sketch and explain the operational features DC servo motor. **(04)**
  
- 3A.** Explain essential features of Tool magazines and discuss its types. **(03)**
- 3B.** Explain the benefits of using Group Technology in manufacturing. **(02)**
- 3C.** Write part program for fig.1 shown below considering cut per pass as 1mm. **(05)**
  
- 4A.** Sketch & explain the working principle of Polar Body and arm robot configuration with its application. **(03)**
- 4B.** Sketch and explain the recirculating ball screw mechanism employed in CNC machines. **(04)**
- 4C.** Explain the different types of sensors used in robots. **(03)**
  
- 5A.** Define tool path linearization & discuss its benefits. **(02)**
- 5B.** Discuss different types of CMM configurations. **(03)**
- 5C.** Explain the concept of FMS, discuss machine flexibility and Routing flexibility and list its merits and demerits. **(05)**

- 6A.** Write a part program for the fig.2 shown below considering cut per pass as 1mm. **(08)**
- 6B.** List the parts classification based on the part design attributes. **(02)**

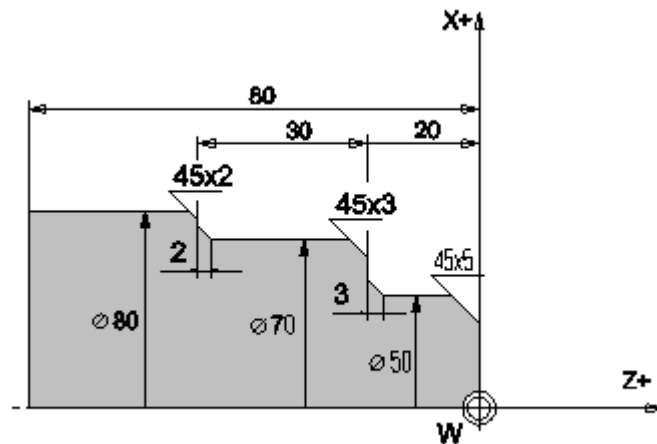
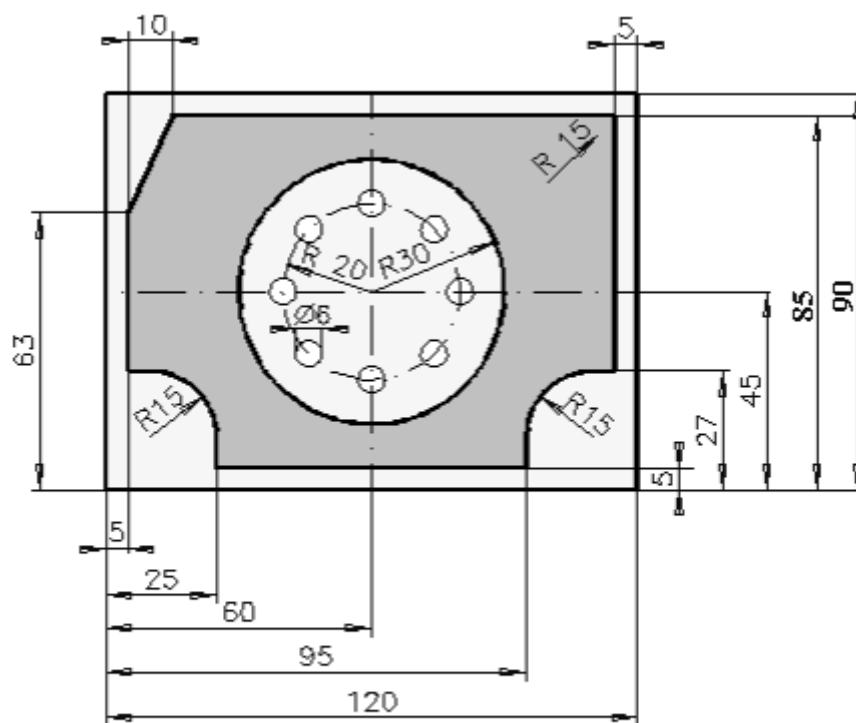


Fig.1



depth of the contour and circular pocket = 5 mm

Fig. 2