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INTERNATIONAL CENTRE FOR APPLIED SCIENCES
 (Manipal University)
IV SEMESTER B.S. DEGREE EXAMINATION – APRIL/MAY 2017
SUBJECT: MEASUREMENTS AND INSTRUMENTATION (MET 242)
 (BRANCH: MECHATRONICS ENGINEERING)
Saturday, 29 April 2017

Time: 3 Hours

Max. Marks: 100

- ✓ Answer ANY FIVE full Questions.
- ✓ Missing data, if any, may be suitably assumed.

- 1A.** Prove that in a Permanent Magnet Moving Coil Mechanism (PMMC), the angular deflection is linearly proportional to the current flowing through it.
- 1B.** What is the working principle of Cathode Ray Oscilloscope (CRO)? Draw and explain the block diagram of a CRO.
- 1C.** Define Seebeck Effect. Describe the three laws of thermocouple with diagram. **(6+8+6)**
- 2A.** Differentiate between static and dynamic characteristics. Define accuracy and precision.
 Draw suitable diagrams for the following:
- High Precision and High Accuracy
 - High Precision and Low Accuracy
 - Low Precision and High Accuracy
 - Low Precision and Low Accuracy.
- 2B.** Determine the value of:
- i. Shunt Resistance in a DC Ammeter (Shunt Resistor), and
 - ii. Multiplier Resistance in a DC Voltmeter (Multiplier Resistor).
- Draw the circuit diagram for both.
- 2C.** Explain the system of Bourdon Tube Pressure Gauge. **(5+10+5)**
- 3A.** The following measurements were taken with an analogue meter of the current flowing in a circuit (the circuit was in steady state and therefore, although the measurements varied due to random errors, the current flowing was actually constant):
 21.5mA, 22.1mA, 21.3mA, 21.7mA, 22.0mA, 22.2mA, 21.8mA, 21.4mA, 21.9mA, 22.1mA
- Calculate:
- i. The Mean Value
 - ii. The Median Value, and
 - iii. The Standard Deviation.

- 3B.** A Kelvin double bridge each of the ratio arms $P = Q = p = q = 1000 \, \Omega$. The emf of the battery is 100 V and a resistance of $5 \, \Omega$ is included in the battery circuit. The galvanometer has a resistance of $500 \, \Omega$ and the resistance of the link connecting the unknown resistance to the standard resistance may be neglected. The bridge is balanced when the standard resistance $S = 0.001 \, \Omega$. (Refer Figure 1 given below)

- Determine the value of unknown resistance
- Determine the current (approximate value) through the unknown resistance R , at balance.
- Determine the deflection of galvanometer when the unknown resistance R is changed by 0.1 percent from its value at balance. The galvanometer has a sensitivity of $200 \, \text{mm}/\mu\text{A}$.

(10+10)

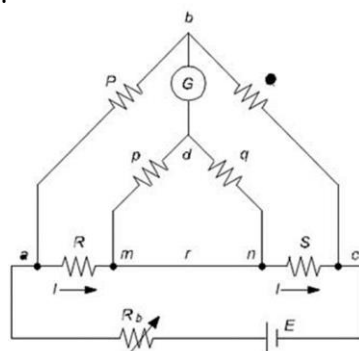


Figure 1

- 4A.** Differentiate between systematic and random error. What are the different sources of static errors? Explain them.
- 4B.** I. Define sensitivity drift and zero drift. What factors can cause sensitivity drift and zero drift in instrument characteristics?
- II. An instrument is calibrated in an environment at a temperature of 20°C and the following output readings y are obtained for various input values x :

y	13.1	26.2	39.3	52.4	65.5	78.6
x	5	10	15	20	25	30

Determine the measurement of sensitivity of instrument in terms of y/x .

- 4C.** Define metrology. List the objectives of metrology.
- 5A.** What is the working principle of Potentiometer? List the parameters that are considered while selecting a potentiometer.
- 5B.** Explain the construction and working principle of Resistance Temperature Detector (RTD).

(8+8+4)

- 5C.** The arms of an AC Maxwell's Bridge are as follows: AB is a non-inductive resistance of 1000Ω in parallel with a capacitor of capacitance $0.5\mu\text{F}$, BC is a non-inductive resistance of 600Ω . CD is an inductive impedance (unknown) and DA is a non-inductive resistance of 400Ω . If a balance is obtained under these conditions, find the value of resistance and inductance of branch CD. (Refer Figure 2 below) (8+8+4)

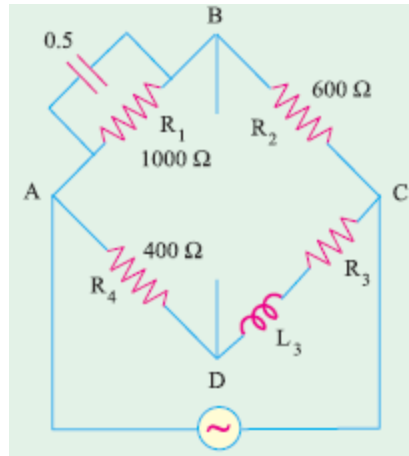


Figure 2

- 6A.** Explain various controls in a Cathode Ray Oscilloscope (CRO).
- 6B.** Explain in brief the elements of a measurement system. Draw the block diagram also.
- 6C.** Discuss how the sensing capacity of an ultrasonic sensor varies with respect to:
- Target Size
 - Target to sensor distance
 - Temperature of the surroundings
 - Type of target to be sensed
- (8+8+4)
- 7A.** With the help of a diagram, explain the working principle of Autocollimator.
- 7B.** Explain Limit Gauges and Taylor's Theory of Gauging.
- 7C.** Define the term blind zone with respect to ultrasonic sensor. With the help of a diagram, explain the different sensing distances of ultrasonic sensor. (8+6+6)
- 8A.** Explain the construction and working of inductive sensor, with a neat sketch.
- 8B.** Explain the desirable features of sensors.
- 8C.** Write a short note on Incremental Encoder. Also, list the applications of encoders. (8+6+6)

