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MANIPAL INSTITUTE OF TECHNOLOGY
MANIPAL

A Constituent Institution of Manipal University

VI SEMESTER B.TECH. (AUTOMOBILE ENGINEERING)

END SEMESTER EXAMINATIONS, APRIL/MAY 2017

SUBJECT: COMPUTER INTEGRATED MANUFACTURING [AAE 4008]

**REVISED CREDIT SYSTEM
 (27/04/2017)**

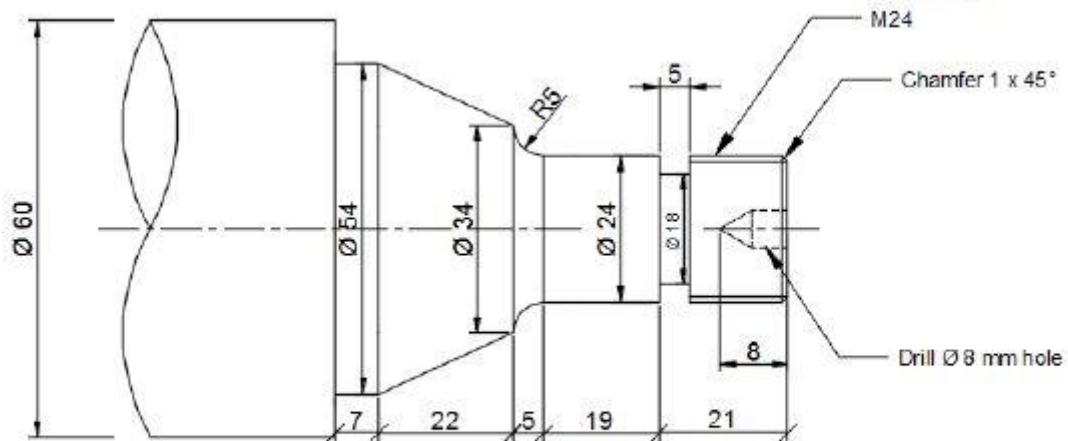
Time: 3 Hours

MAX. MARKS: 50

Instructions to Candidates:

- ❖ Answer **ALL** the questions.
- ❖ Missing data may be suitable assumed.

- 1A.** Explain the different types of sensors used in robots **(03)**
- 1B.** Explain the methods of improving accuracy in NC machines **(03)**
- 1C.** Explain the steps involved in production flow analysis. **(04)**
- 2A.** Explain any three types of End-effectors used in industrial robots with proper applications. **(03)**
- 2B.** Write a part program to obtain the component as shown in the Fig. 2B **(05)**
- 2C.** Can NC machines completely replace the conventional machining system? **(02)**
 Justify your answer with a suitable reason.
- 3A.** Explain the principle of operation of AGV's with an example and mention the advantages of FMS. **(03)**
- 3B.** Write a part program to obtain the component as shown in the Fig. 3B **(04)**
- 3C.** Write a part program to obtain the component as shown in the Fig. 3C **(03)**
- 4A.** Sketch and explain the working of a linear interpolator. **(03)**
- 4B.** Draw the sketch of following robot configuration and show clearly all the movements for body-arm assembly. **(04)**
 - i. Cartesian
 - ii. Cylindrical
- 4C.** Explain the meaning of the following with reference to robots **(03)**
 - (i) Control resolution
 - (ii) Accuracy
 - (iii) Repeatability
- 5A.** Write a part program to obtain the component as shown in the Fig. 6A **(07)**
- 5B.** Explain the composite part concept used in group technology with an example. **(03)**



Note: 1. Blank dia = 60 mm
2. Use grooving tool width 3 mm

Fig: 2B

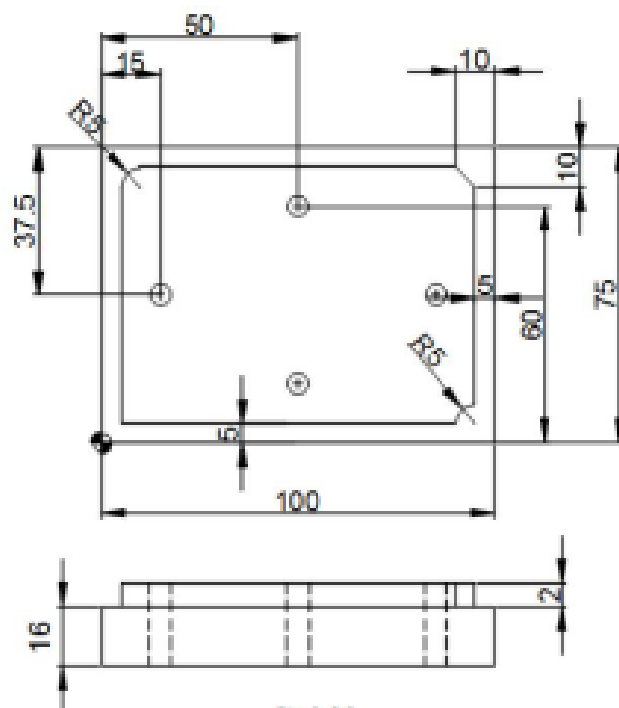


Fig: 3B

Note:

1. Thickness of raw material 20mm

Tools to be used [Diameters]:

1. 50mm face mill

2. 20mm end mill

3. 5mm drill tool

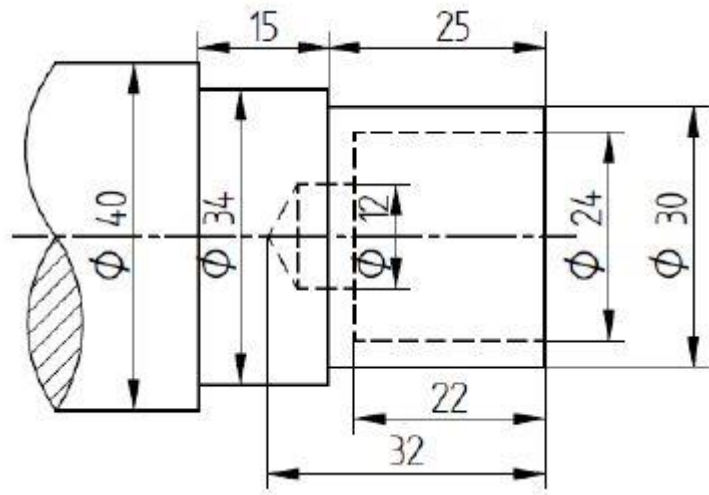


Fig :3C

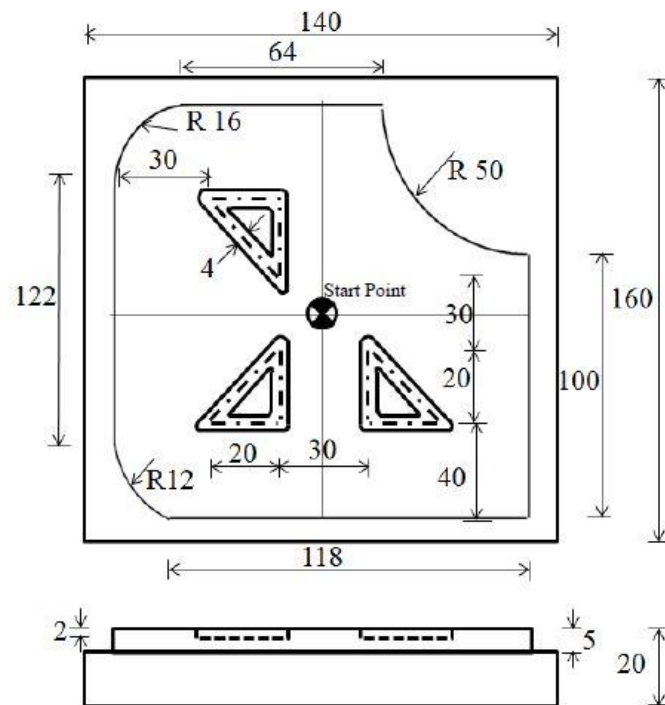


Fig: 6A