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MANIPAL INSTITUTE OF TECHNOLOGY
MANIPAL
A Constituent Institution of Manipal University

SIXTH SEMESTER B.TECH. (INSTRUMENTATION & CONTROL ENGG.)

END SEMESTER EXAMINATIONS, APRIL/MAY 2017

SUBJECT: Embedded System Design [ICE 4002]

Time: 3 Hours

MAX. MARKS: 50

Instructions to Candidates:

- ❖ Answer **ALL** the questions.
- ❖ Draw diagram wherever required

- 1A.** Explain different design technologies of embedded system. **4**
- 1B.** Define “renaissance engineer” and explain its importance in the present market scenario with an example. **2**
- 1C.** What is single-purpose processor? What are the benefits of choosing a single-purpose Processor over a general-purpose processor? **2**
- 1D.** List the characteristics of embedded system that distinguish it from other computing systems. **2**
- 2A.** Explain, how data memory is partitioned and how data transfer will take place between CPU to cache. **4**
- 2B.** Explain the operation of different cache mapping technique with one constraints for each technique **4**
- 2C.** Briefly explain scratchpad memory. **2**
- 3A.** Illustrate how communication & synchronization is done among process control devices. **5**
- 3B.** Explain how page fault occurs and how the fault is serviced. Give over view about TLB. **5**
- 4A.** An embedded system is controlling the operation of a lift, which move to respective floor as per request and door will be open for 10 sec. When there is a fire alarm, the lift will be moving to first floor irrespective of request. (a) Draw the FSMD state diagram for this system. (b) Separate the FSMD into an FSM+D. **5**
- 4B.** Write a generic PID controller program in C language with comments. **5**
- 5A.** Define the following terms with an example: finite-state machines, concurrent processes, real-time systems, and real-time operating system. **4**

- 5B.** Develop a closed loop control system for a car cruise control. Implement different controller response such as P, PI, PD and PID for the developed loop and draw its responses. **6**

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