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**MANIPAL INSTITUTE OF TECHNOLOGY**  
**MANIPAL**

*A Constituent Institution of Manipal University*

**V SEMESTER B.TECH. (MECHATRONICS ENGINEERING)**

**END SEMESTER EXAMINATIONS, NOV 2017**

**SUBJECT: MICROCONTROLLER BASED SYSTEM DESIGN**

**[MTE 3103]**

**REVISED CREDIT SYSTEM**

**(24/11/2017)**

Time: 3 Hours

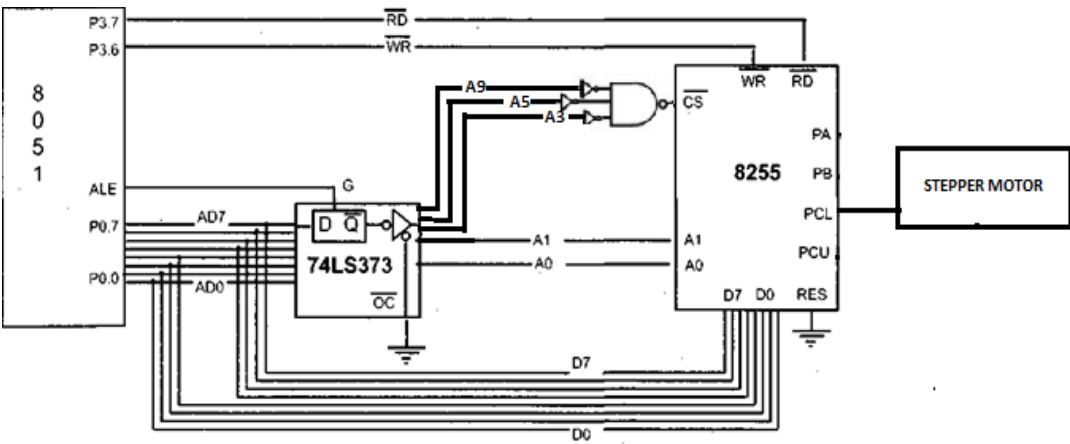
MAX. MARKS: 50

**Instructions to Candidates:**

- ❖ Answer **ALL** the questions.
- ❖ Data not provided may be suitably assumed

<b>1A.</b>	Write a assembly program using interrupts to do the following: (a) Receive data serially and send it to P0, (b) Have P1 port read and transmitted serially, and a copy given to P2, (c) using timer 0 generate a square wave of 5kHz frequency on P0.1. Assume that XTAL=11.0592Mhz. Set the baud rate at 4800.	<b>05</b>
<b>1B.</b>	With a neat pin structure, elucidate the operation of port 1 pin that is to be operated as an input.	<b>03</b>
<b>1C.</b>	Explain the following instructions (a) JBC ACC.7, next                      (b) SWAP A (c) NOP    (d) MOVC A, @A+DPTR	<b>02</b>
<b>2A.</b>	An IR sensor is a part of a visitor counter module that is present at the entrance of a store. The sensor is connected to input pin 3.4 of an 8051 microcontroller. Write an ALP to display the visitor count on port 1 & port 2. The information is to be refreshed every 1 second. Once the count reaches 60,000, process is to be stopped. XTAL = 22MHz.	<b>04</b>
<b>2B.</b>	Assume that register A has packed BCD, write a program to convert packed BCD to two ASCII numbers and place them in R2 and R6.	<b>03</b>



3C.	List any four differences between Harvard & Von Neumann architecture.	02
4A.	Write a short note on the following: a. Sampling a low-level triggered interrupt b. Significance of the INTR pin in ADC	03
4B.	<p>A stepper motor interface is connected to 8051 through 8255 as shown in fig.Q4b. Write a program to rotate the stepper motor in the following sequence. 1 revolution CW, 1 revolution ACW, 2 revolutions CW, 2 revolutions ACW ... till it reaches 10 revolutions CW and 10 revolutions ACW. After this the process should repeat from the start. Step angle of the motor is <math>1.8^\circ</math>. Use a wave drive sequence.</p>  <p style="text-align: center;">FIG. Q4b</p>	05
4C.	With a neat bit diagram, explain the Interrupt Priority register. Also, if the IP register has a value 000010101B, in what order will the interrupts be executed?	02
5A.	Write a program to copy the value 55H into RAM memory locations 40H to 41H using (a) direct addressing mode, (b) register indirect addressing mode without a loop, and with a loop	03
5B.	Write a program to send the message "The Earth is Beautiful" to serial port. Assume a SW is connected to pin P1.2. Monitor its status and set the baud rate as follows:(without interrupts) SW = 0, 4800 baud rate SW = 1, 9600 baud rate Assume XTAL = 11.0592 MHz, 8-bit data, and 1 stop bit.	04
5C.	What is the importance of the SMOD bit (D7 bit) of the PCON register? Write a program to get the value X from P1 and send $X^2$ to P2, continuously.	03