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MANIPAL INSTITUTE OF TECHNOLOGY
MANIPAL

A Constituent Institution of Manipal University

SEVENTH SEMESTER B.TECH. (INSTRUMENTATION AND CONTROL ENGG.)

END SEMESTER EXAMINATIONS, NOV - 2017

SUBJECT: MULTI SENSOR DATA FUSION [ICE 4011]

Duration: 3 Hour

Max. Marks:50

Instructions to Candidates:

- ❖ Answer **ALL** the questions.
- ❖ Missing data may be suitably assumed.

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| 1A | Explain fusion node and its properties with necessary diagrams. | 5 |
| 1B | With an example, explain each type of sensor configuration | 3 |
| 1C | Distinguish between sensor fusion and sensor data fusion | 2 |
| 2A | Explain the different network topologies used in data fusion. | 4 |
| 2B | What is sensor uncertainty? List the different types of sensor uncertainty. | 3 |
| 2C | Explain any two methods for sampling common training data set used in fusion | 3 |
| 3A | When is semantic alignment used in data fusion? Explain clustering algorithm of semantic alignment. | 4 |
| 3B | Describe spatial – temporal transformation in sensor data fusion. | 3 |
| 3C | With a neat diagram discuss the characteristic functional flow across data fusion levels. | 3 |
| 4A | Describe the role of resource management in information processing cycle. | 4 |
| 4B | Compare the working of Thompoulo's and Pau's framework with an example | 4 |
| 4C | List the key features of Dasarathy's data fusion I/O model. | 2 |
| 5A | Explain nearest neighbor, track splitting and multiple hypothesis methods of data association | 4 |
| 5B | Describe the process of data flow in omnibus framework | 3 |
| 5C | Illustrate the working of evidence combination type of decision making | 3 |