

Question Paper

Exam Date & Time: 05-Jun-2018 (09:30 AM - 12:30 PM)



MANIPAL ACADEMY OF HIGHER EDUCATION

INTERNATIONAL CENTRE FOR APPLIED SCIENCES IV SEMESTER B.S. DEGREE MAKE-UP EXAMINATION-MAY/JUNE 2018

DATE: 5 JUNE 2018

TIME: 9.30 AM TO 12.30 PM

Control Systems [EE 241]

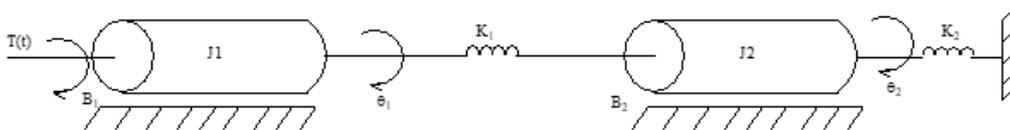
Marks: 100

Duration: 180 mins.

Answer ANY FIVE full Questions.

Missing data, if any, may be suitably assumed

- 1) Draw the root locus of a system with $G(s)H(s) = \frac{K(s+3)}{s(s+2)}$ and find the stability. Prove that a part of the root locus is a circle. (12)
- A) stability. Prove that a part of the root locus is a circle. (8)
- B) For the mechanical system write the differential equations. Draw the corresponding electrical network based on torque-current analogy. (8)



- 2) Explain lag and lead compensating networks. (6)
- A) Explain lag and lead compensating networks. (6)
- B) Draw the block diagram for the given electrical circuit shown in Fig 2B. find $\frac{V_o(s)}{V_i(s)}$ using block diagram reduction method and verify the answer using Mason's gain formula. (14)

Mason's gain formula.

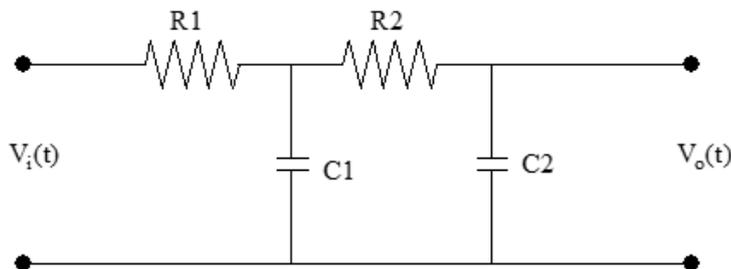


Fig 2B

- 3) A unity negative feedback system is characterised by $G(s) = \frac{10}{(s+1)}$, Find the error as a function of time t and evaluate the same when $r(t) = 1 + 2t$. What is the steady state error? (8)
- A) error as a function of time t and evaluate the same when $r(t) = 1 + 2t$. What is the steady state error? (8)
- B) Write the differential equations for the mechanical system shown in Fig 3B. Draw the corresponding electrical circuit based on force current and force voltage analogies. (12)

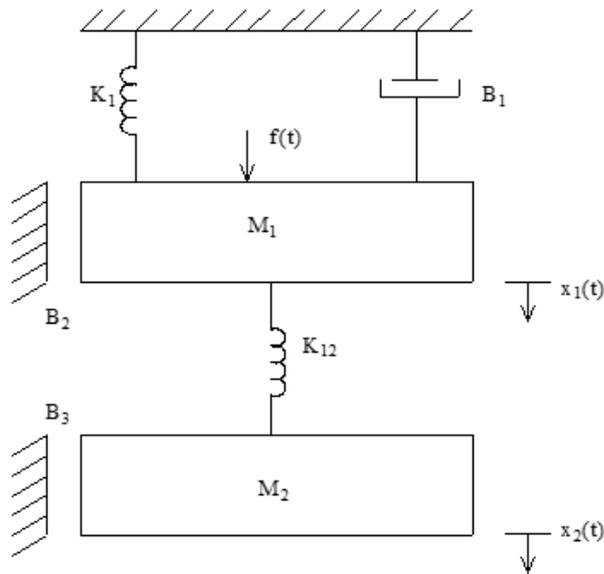


Fig 3B

- 4) For a second order system subjected to a step input derive expressions for (8)
- A) i) peak time t_p
ii) peak overshoot
- B) Given $G(s)H(s) = \frac{K(s+1)}{(s^2 - 2s + 2)}$, Draw the root locus and find the system stability. Prove that $s = +j2$ lies on root locus. (12)
- 5) Given $G(s)H(s) = \frac{K}{s(1 + 0.2s)(1 + 0.05s)}$ Find K such that the phase margin is 40° and 0° . (12)
- A)
- B) Obtain the state model for the system described by $\frac{y(s)}{u(s)} = \frac{s^2 + 2s + 1}{(s^3 + 6s^2 + 10s + 5)}$ (8)
- 6) Given $G(s)H(s) = \frac{K}{s(1 + 0.1s)(1 + s)}$, Determine the value of K so that gain margin is 6dB. (10)
- A)
- B) A feedback control system is characterised by $G(s)H(s) = \frac{K}{s(s + \alpha)}$. Determine K and α so that resonant peak $M_r = 1.04$ and resonant frequency $\omega_r = 11.55$ rads/sec. (10)
- 7) (8)
- A)

Find the transfer function $G(s)$ and frequencies ω_{g1} and ω_{g2} for the bode plot shown in Fig 7A.

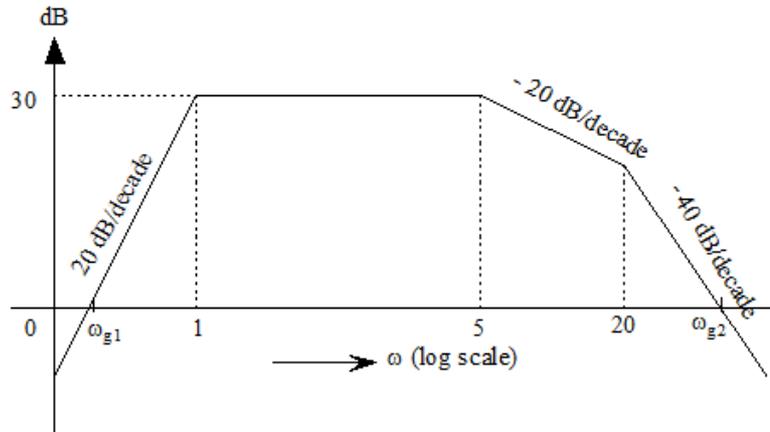


Fig 7A

B) Sketch the root locus for $G(s)H(s) = \frac{K}{s(s+2)(s^2+2s+5)}$ and find the stability. (12)

8) (12)

A) For the system represented by the following equations. Find the transfer function $\frac{x(s)}{u(s)}$ by signal flow graph technique.

$$x = x_1 + \beta_3 u$$

$$\bullet \quad x_1 = -a_1 x_1 + x_2 + \beta_2 u$$

$$\bullet \quad x_2 = -a_2 x_1 + \beta_1 u$$

B) A second order unity feedback system is characterised by the following transfer function $\frac{C(s)}{R(s)} = \frac{361}{(s^2 + 16s + 361)}$ Find, (8)

- a) ζ b) ω_n c) t_s settling time d) peak time t_p e) peak overshoot

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