


SECOND SEMESTER M.TECH. (CONTROL SYSTEMS)
END SEMESTER EXAMINATIONS, APRIL - 2018
SUBJECT: SOFT COMPUTING TECHNIQUES [ICE 5222]

Duration: 3 Hour

Max. Marks:50

Instructions to Candidates:

- ❖ Answer **ALL** the questions.
- ❖ Missing data may be suitably assumed.

- 1A** Let \mathcal{X} be the universe of satellites of interest, as defined below: 2
 Let $\mathcal{X} = \{a12, x15, b16, f4, f900, v111\}$, Let \bar{A} be the fuzzy set of INSAT-A satellite:
 $\bar{A} = \left\{ \frac{0.2}{a12} + \frac{0.3}{x15} + \frac{1}{b16} + \frac{0.1}{f4} + \frac{0.5}{v111} \right\}$ Let \bar{B} be the fuzzy set of INSAT-B satellite:
 $\bar{B} = \left\{ \frac{0.1}{a12} + \frac{0.25}{x15} + \frac{0.9}{b16} + \frac{0.7}{f4} + \frac{0.3}{f900} + \frac{0.2}{v111} \right\}$. Find the following sets of combinations for these two sets:
 a) $\bar{A} \cup \bar{B}$; b) $\bar{A} \cap \bar{B}$; c) $\bar{\bar{A}}$; d) $\bar{\bar{B}}$; e) $\bar{\bar{A} \cup \bar{B}}$; f) $\bar{\bar{A} \cap \bar{B}}$; g) $\bar{\bar{A} \cup \bar{B}}$; h) $\bar{\bar{A} \cap \bar{B}}$
- 1B** Explain with suitable example and diagram fuzzy equivalence relation. 2
- 1C** With suitable examples, explain how membership assignment is performed using intuition and inference method. 3
- 1D** Find the defuzzified value using centroid method for the figure shown in Fig.Q1D. 3

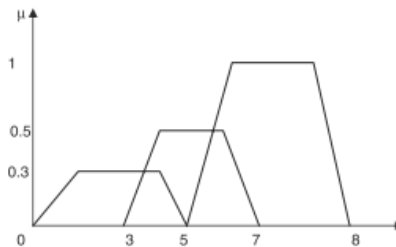


Fig.Q1D

- 2A** Discuss in detail on Decomposition of rules and also the formation of rules in a Mamdani FIS. 5
- 2B** Develop an FIS model for controlling the water level and temperature in the boiler using Mamdani fuzzy inference models. Assume your own linguistic variables. 3
- 2C** Describe in brief the design elements of a general fuzzy logic control system with its block diagram 2
- 3A** Find the weights using perceptron network for the ANDNOT function when all the inputs are prescribed only one time. Use bipolar inputs and targets. 3

- 3B** Implement XOR function using McCulloch –Pitts neuron (consider binary data). 3
- 3C** Construct and test an LVQ net with five vectors assigned to two classes. The given vectors along with the classes are as shown in the Table Q3C. 4

Table Q3C

Vector	Class
[0 0 1 1]	1
[1 0 0 0]	2
[0 0 0 1]	2
[1 1 0 0]	1
[0 1 1 0]	1

- 4A** Consider a Kohonen self-organizing net with two cluster units and five input units. The weight vectors for the cluster units are given by 2

$$w_1 = [1.0 \ 0.9 \ 0.7 \ 0.5 \ 0.3]$$

$$w_2 = [0.3 \ 0.5 \ 0.7 \ 0.9 \ 1.0]$$

Use the square of the Euclidean distance to find the winning cluster unit for the input pattern $x = [0.0 \ 0.5 \ 1.0 \ 0.5 \ 0.0]$. Using a learning rate of 0.25, find the new weights for the winning unit.

- 4B** Consider an ART1 network for clustering four input vectors with low vigilance parameter of 0.4 into three clusters. The four input vectors are [0 0 0 1], [0 1 0 1], [0 0 1 1] and [1 0 0 0]. Assume the necessary parameters needed. 3

- 4C** Generate a neural net using BPN algorithm for XOR function. The architecture and the values of initial weights and biases are shown in Fig.Q4B. 5

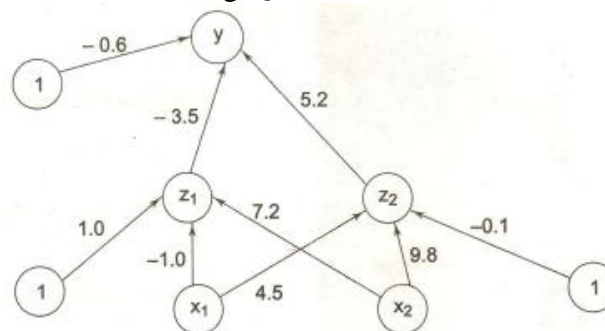


Fig. Q4B

- 5A** Discuss the Applications of neural network in Pattern recognition and Control system applications. 4
- 5B** Describe the three main operators in genetic algorithm 3
- 5C** Construct a Maxnet with four neurons and inhibitory weight $\varepsilon = 0.2$, given the initial activations as follows: $a_1(0) = 0.3$; $a_2(0) = 0.5$; $a_3(0) = 0.7$; $a_4(0) = 0.9$ 3