



## VII SEMESTER B.TECH. (INFORMATION TECHNOLOGY / COMPUTER AND COMMUNICATION ENGINEERING)

END SEMESTER EXAMINATIONS, NOVEMBER 2018

SUBJECT: PROGRAM ELECTIVE IV: COMPUTER VISION [ICT 4018]

REVISED CREDIT SYSTEM

(27/11/2018)

Time: 3 Hours

MAX. MARKS: 50

### Instructions to Candidates:

- ❖ Answer **ALL** the questions.
- ❖ Missing data if any, may be suitably assumed.

- 1A. Explain median filter. What advantage does a median filter have over a mean filter? Is median filter a kind of convolution? Using a window size of three apply a median filter for the 1D signal  $X=(2, 80, 60, 3, 4, 7, 6, 10, 10, 2)$ . 5
- 1B. List and explain any three constraints/criterion to consider into account while designing for a good edge detector. 3
- 1C. Prove that the composition of two isometries is an isometry. 2
  
- 2A. Explain how Scale Invariant Feature Transform can be used to build for
  - i) Detector 5
  - ii) Descriptor
- 2B. For the below assertion, say whether it is true or false and support your answer with example or counter example.
  - i) As  $\sigma$  increases, less pixels are involved in the average.
  - ii) Corner location is covariant w.r.t. rotation.
  - iii) Two dimensional Gaussian can be separated into 2 one-dimensional Gaussians. 3
- 2C. Explain hysteresis threshold step used in Canny edge detection method. 2
  
- 3A. Derive the equation for optical flow. Explain how Horn and Schunck method is used to find the optical flow. 5
- 3B. Consider a vector whose endpoint is  $(X_1, Y_1, Z_1)$ . Let  $R$  denote the length of the vector and  $\phi$  denote the angle the vector makes with X-axis. Assume that the vector is rotated by angle  $\Theta$  around the Z-axis in the counter clockwise direction. Find
  - i) The new coordinates  $(X_2, Y_2, Z_2)$  of the point after rotation.
  - ii) The rotation matrix.
  - iii) The inverse rotation matrix. 3

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| <b>3C.</b> | Explain how final feature vectors are generated for 64 x 128 image in HOG descriptor.           | <b>2</b> |
| <b>4A.</b> | Write an algorithm for finding fundamental matrix.  | <b>5</b> |
| <b>4B.</b> | Explain Histogram based threshold method to segment the text in the gray scale image.           | <b>3</b> |
| <b>4C.</b> | Explain probabilistic skin classification method.   | <b>2</b> |
| <b>5A.</b> | Write step by step procedure for face recognition. Give the steps for training and recognition. | <b>5</b> |
| <b>5B.</b> | Write Hough transform algorithm for fitting circle using polar form of equation of a circle.    | <b>3</b> |
| <b>5C.</b> | Briefly explain any four feature of an image.   | <b>2</b> |