



**SIXTH SEMESTER B.TECH. (E & C) DEGREE END SEMESTER EXAMINATION**  
**JUNE 2019**

**SUBJECT: LINEAR ALGEBRA FOR SIGNAL PROCESSING (ECE - 4008)**

**TIME: 3 HOURS**

**MAX. MARKS: 50**

**Instructions to candidates**

- Answer **ALL** questions.
- Missing data may be suitably assumed.

1A. Given matrix  $A$  and vector  $b$  as follows:

$$A = \begin{bmatrix} 2 & 2 & 4 \\ 8 & 9 & 19 \\ 2 & 2 & 5 \end{bmatrix} \quad b = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

i) Perform  $LU$  factorization of  $A$ .

ii) Solve the system  $Ax=b$  by solving the two triangular systems  $Lc=b$  and  $Ux=c$ .

- 1B. Let  $X=3v_1+2v_2-v_3$  with respect to the basis vectors  $v_1=[1 \ 1 \ 1]^T$ ,  $v_2=[2 \ 3 \ 2]^T$  and  $v_3=[1 \ 5 \ 4]^T$ . Find the coordinates of vector  $X$  with respect to a new basis defined by  $u_1=[1 \ 1 \ 0]^T$ ,  $u_2=[1 \ 2 \ 0]^T$  and  $u_3=[1 \ 2 \ 1]^T$
- 1C. Express the vector  $v=[1 \ -2 \ 5]^T$  as a linear combination of the vectors  $e_1=[1 \ 1 \ 1]^T$ ,  $e_2=[1 \ 2 \ 3]^T$ , and  $e_3=[2 \ -1 \ 1]^T$ .

(4+3+3)

- 2A. Given that a received signal is sum of a single sinusoidal frequency and white noise, and given its autocorrelation samples as below, estimate the frequency of the single sinusoidal in this signal.

$$r(-1)=2.0140-j3.4560, r(0)=4.3960 \text{ and } r(1)=2.0140+j3.4560$$

- 2B. Consider the signal  $r(t)=\sqrt{T/3}$  for  $0 < t < T/3$  and 0 for all other values of  $t$ . Let the set  $S_1=\{r(t), r(t-(T/3)), r(t-(2T/3))\}$  form an orthonormal basis for a vector space  $V$  (spanned by this basis). Now consider another set  $S_2=\{-r(t), \sqrt{2}r(t-(T/3))+r(t-(2T/3)), r(t-(2T/3))\}$  which forms an orthonormal basis for the *same* vector space  $V$ . Give the transition matrix for a change of basis from  $S_2$  to  $S_1$ .
- 2C. The eigenvalues of a projection matrix can take only two values. Which are these values? Prove your answer.

(4+3+3)

- 3A. Consider the matrix  $A$  as given below.

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \\ 2 & 3 & 1 \end{bmatrix}$$

- i) Is  $A$  a circulant matrix?

- ii) Multiply any one column of  $A$  by a 3 point DFT matrix.
- iii) Compute the eigenvalues of  $A$ .
- iv) Comment on the results of (ii) and (iii) above.

3B. Perform  $QR$  factorization of the matrix  $A$  given below and solve the system  $Ax=b$  using the  $QR$  factorization method where  $b = [7 \ 11 \ 17]^T$ .

$$A = \begin{bmatrix} 1 & 2 & 1 \\ -2 & 3 & 4 \\ 1 & 0 & 5 \end{bmatrix}$$

3C. Let  $X=3v_1+2v_2-v_3$  with respect to the basis vectors  $v_1=[1 \ 1 \ 1]^T$ ,  $v_2=[2 \ 3 \ 2]^T$  and  $v_3=[1 \ 5 \ 4]^T$ . Find the coordinates of vector  $X$  with respect to a new basis defined by  $u_1=[1 \ 1 \ 0]^T$ ,  $u_2=[1 \ 2 \ 0]^T$  and  $u_3=[1 \ 2 \ 1]^T$

(4+3+3)

4A. Consider a vector space  $V$  spanned by the set

$$\{\exp(j2\pi x/A), \exp(-j2\pi x/A), \exp(j4\pi x/A), \exp(-j4\pi x/A), 5\cos((2\pi x/A)+\pi/3)\}$$

- i) Is  $10\cos((4\pi x/A)+2\pi/3)$  an element of  $V$ ?
- ii) Give a basis set for  $V$
- iii) In the basis you have given, what are the coordinates of  $6\sin((4\pi x/A)+2\pi/3)$ ?

NOTE: All  $x$  dependent functions in this question are in the interval  $-A/2$  to  $A/2$ .

4B. Use the Gauss-Jordan method to find the inverse of the matrix  $A$  given as

$$A = \begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix}$$

4C. Let  $a$  and  $b$  be two vectors in the three dimensional Cartesian space with  $x$ ,  $y$  and  $z$  coordinates as  $a_x$ ,  $a_y$ , and  $a_z$  &  $b_x$ ,  $b_y$ , and  $b_z$  respectively. If the vector cross product ( $a \times b$ ) between these two vectors can be expressed as the product  $Ac$  where  $A$  is a matrix with its elements chosen appropriately from the set of coordinates of vector  $a$ , and  $c$  is a vector with its elements as the coordinates of vector  $b$ . i.e  $c=[b_x, b_y, b_z]^T$ , which is the matrix  $A$ ?

(4+3+3)

5A. Perform a singular value decomposition on the matrix  $A$  given below and with the help of this decomposition determine its Moore-Penrose pseudo inverse.

$$A = \begin{bmatrix} 1 & 2 & 3 \\ -1 & 3 & -2 \end{bmatrix}$$

5B. Demonstrate the relationship between linear least squares solution of over determined systems and the concept of vector projection.

5C. Find the eigenvalues and eigenvectors of a matrix  $A$  that satisfies the following relations

$$\text{i) } A \begin{bmatrix} -0.6535 \\ 0.7569 \end{bmatrix} = \begin{bmatrix} 0.8604 \\ -0.9966 \end{bmatrix} \text{ and ii) } A \begin{bmatrix} -0.4204 \\ -0.9073 \end{bmatrix} = \begin{bmatrix} -2.2351 \\ -4.8240 \end{bmatrix}$$

(4+3+3)