



# MANIPAL INSTITUTE OF TECHNOLOGY

MANIPAL

(A constituent unit of MAHE, Manipal)

**FIFTH SEMESTER B.TECH. (INSTRUMENTATION AND CONTROL ENGG.)**

**END SEMESTER DEGREE EXAMINATIONS, DECEMBER - 2019**

**SUBJECT: CONTROL SYSTEM COMPONENTS [ICE 3105]**

TIME: 3 HOURS

MAX. MARKS: 50

**Instructions to candidates :Answer ALL questions and missing data may be suitably assumed.**

- 1A. What is servomechanism? Explain with an example.
- 1B. Describe the working of a field controlled DC servo motor with a neat diagram.
- 1C. Explain synchro system operation with necessary diagrams. (2+4+4)
- 2A. How Hybrid stepper motor is different from permanent magnet type and variable reluctance type stepper motor?
- 2B. Explain the torque vs. angle characteristics of a stepper motor with necessary waveforms.
- 2C. Draw the instrument line symbols for the following. 1. Pneumatic signal 2. Electric Signal 3. Capillary tube 4. Software or data link 5. Mechanical link 6. Sonic signal (4+3+3)
- 3A. Design a pneumatic lift system with UP and DOWN functions using valves.
- 3B. What is valve flow coefficient? How is it important in valve sizing? Explain with example.
- 3C. What is rangeability of a valve? Explain how rangeability varies with valve characteristics. (3+4+3)
- 4A. Draw the sketch of relay type controller and describe its working.
- 4B. Classify the Followers based on its motion. Explain each type with neat diagram.
- 4C. Explain the working of balanced vane pump with the help of a neat diagram. (3+3+4)
- 5A. Explain the construction and working of gerotor pump.
- 5B. Describe the different types of gyroscopes and their field of application.
- 5C. Define the following for a gyroscope. 1. Angular velocity of precession 2. Axis of precession 3. Precessional angular motion. (3+4+3)

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