Reg. No.					



V SEMESTER B.TECH. (MECHATRONICS ENGINEERING) END SEMESTER EXAMINATIONS, NOV 2019

SUBJECT: MICROCONTROLLER BASED SYSTEM DESIGN [MTE 3103] (25/11/2019)

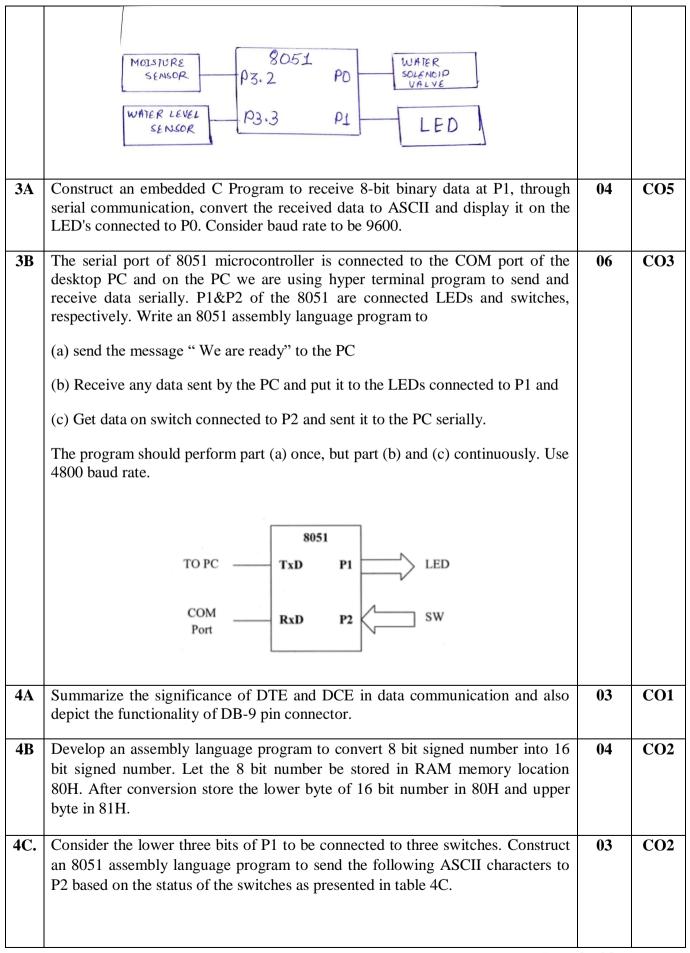
Time: 3 Hours MAX. MARKS: 50

Instructions to Candidates:

- ❖ Answer **ALL** the questions.
- Data not provided may be suitably assumed

1A.	Classify different ranges of jump and call instructions available in 8051 with suitable design layout.	03	CO1
1B.	Develop an Embedded C program to compare two eight bit numbers NUM1 and NUM2 and reflect your result as: a) If NUM1 <num2, 2fh="" b)="" bit="" if="" location="" lsb="" num1="" of="" set="">NUM2, SET MSB bit of location 2FH c) If NUM1=NUM2, Clear both LSB and MSB of bit addressable memory location 2F.</num2,>	03	CO5
1C.	Consider any unsigned number N. Using the formula $Y = \frac{1}{2} \left(x + \frac{N}{x} \right)$, Y can be approximated to the square root of N. Develop an assembly language program to implement the formula Y used to obtain square root of N and store the result in R2.	04	CO2
2A.	Develop an embedded C program to generate pulse train of 2 second on pin P2.4 using timer1 in mode 1. Consider XTAL=22MHz.	03	CO5
2B.	Develop an assembly language program for an irrigation system designed using moisture and water-level sensors connected to 8051 microcontroller. The moisture sensor will be used to measure the moisture level of the soil every 10 seconds. When the moisture level falls below 20%, the water solenoid valve will be opened to irrigate the soil. When the moisture level is above 70%, the water solenoid valve will be closed. The water tank will be used as water source in the irrigation system. The water level in this tank will be checked every 50 seconds (using the comparator module) by the water-level sensor. If the water level falls below 20%, it is indicated by displaying it on LED. Pictorial representation of the setup is depicted below.	07	CO4

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		SW1	SW2	SW3	ASCII character to be displayed			
		0	0	0	'M'			
		0	0	1	'A'			
		0	1	0	'D'			
		0	1	1	'A'			
		1	0	0	'M'			
		1	0	1	'0'			
		1	1	0	'1'			
		1	1	1	·2·			
				l	Table 4C	I		
5A.	Examining the state the following inst				ents of the register and SP are in hex.	after execution of	03	CO1
	MOV SP, MOV R2, MOV R1, MOV R4, PUSH 2 PUSH 1 PUSH 4 POP 3 POP 1	#25H #12H						

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