

SEVENTH SEMESTER B.TECH. (INSTRUMENTATION AND CONTROL ENGG.) END SEMESTER DEGREE EXAMINATIONS, NOVEMBER - 2019

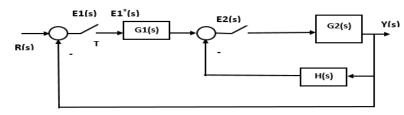
SUBJECT: DIGITAL CONTROL SYSTEM [ICE 4022]

TIME: 3 HOURS

MAX. MARKS: 50

Instructions to candidates : Answer ALL questions and missing data may be suitably assumed.

- 1A. Plot the gain and phase characteristic of ZOH transfer function.
- 1B. Find the response of the following system y(k+2)-3y(k+1)+2y(k)=r(k); Where $r(k)=3^k$. with initial conditions y(0)=0 and y(1)=0.
- 1C. Derive the pulse transfer function of the system shown in Fig. Q1C.





2A. Obtain initial value and final value of

$$X(Z) = \frac{z^2(1 - e^{-T})}{(z - 1)(z - e^{-T})}$$

2B. Determine whether closed loop system given in Fig. Q2B is stable or not (by fundamentals of z plane).

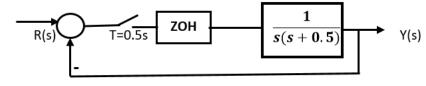
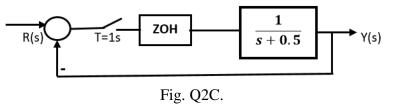


Fig. Q2B

2C. Obtain step, ramp and parabolic error and corresponding gains of the system shown in Fig. Q2C.



(3+3+4)

3A. Find range of K for which the closed loop system is stable using Jury's test if

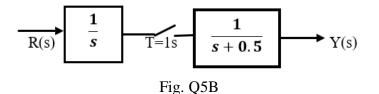
$$G(z) = \frac{K}{z(z-1)} ; \quad T = 2s$$

3B. Determine whether the closed loop system is stable or not using Routh's stability criteria if characteristic equation is $P(Z) = Z^3 - 1.7Z^2 - Z + 0.8 = 0$.

3C. Plot root locus if open loop system is given as

 $G(z) = \frac{K(z+0.52)}{(z-1)(z-0.135)}$. Find the range of K and corresponding 'Z' for which the closed loop system is stable. Also find K at break away and break in points.

- 4A. The function f(t) after passing through the sampler is represented in discrete domain as _____.
- 4B. Plot Bode magnitude and phase plots of $G(z) = \frac{0.368z + 0.264}{(z-1)(z-0.368)}$ and analyse its closed loop stability. (T=1s)
- 4C. Design a lead compensator for system given in (Q. 4B) using bode plot approach so that damping coefficient is 0.7
- 5A. Explain the mapping between S plane and Z plane with necessary diagrams.
- 5B. Derive open loop step response of the Fig. Q5B.



5C. Draw the Nyquist plot of

 $G(Z) = \frac{0.095z}{(z-1)(z-0.9)}$ and determine its closed loop stability.

(2+3+5)

(3+3+4)

(1+5+4)