

SEVENTH SEMESTER B.TECH. (INSTRUMENTATION AND CONTROL ENGG.) END SEMESTER DEGREE EXAMINATIONS, DECEMBER - 2019

SUBJECT: DIGITAL CONTROL SYSTEM [ICE 4022]

TIME: 3 HOURS

MAX. MARKS: 50

Instructions to candidates : Answer ALL questions and missing data may be suitably assumed.

- 1A. Plot the gain and phase characteristic of ZOH system.
- 1B. Find the step response of the system shown in Fig. Q1B. (T=1s), where G(s) = 1/(s+1).



Fig. Q1B.

1C. Derive the closed loop pulse transfer function of the system shown in Fig. Q1C.



(3+3+4)

- 2A. Obtain initial value and final value of $\frac{(z-2)z}{(z+2)(z-3)(z+4)}$
- 2B. Determine the closed loop stability of system by z domain fundamentals if characteristic equation is given by

 $P(Z)=\ Z^3-1.7Z^2-Z+0.8=0$

2C. Obtain step, ramp and parabolic error constants and corresponding errors of the system shown in Fig. Q2C.



3A. Find the range of K for which the closed loop system is stable using Jury's test if

(2+4+4)

$$G(z) = \frac{K}{z(z-0.5)(z+0.5)}$$
; $T = 1 s$

- 3B. Plot root locus if open loop system is given as $G(z) = \frac{Kz}{(z-1)(z-0.2)}$; T = 0.5 s. Find the range of K and corresponding 'Z' for which the closed loop system is stable. Also find K at break away and break in points.
- 3C. The function f(t) after passing through the sampler is represented in discrete domain as ______
- 4A. Plot Bode magnitude and phase plots of $G(z) = \frac{0.368z + 0.264}{(z-1)(z-0.368)}$ and analyze its closed loop stability. (T=1s)
- 4B. Design a lag compensator for system given in (Q. 4A) using Bode plot approach so that overshoot of the desired output is $\leq 15\%$
- 5A. Determine whether the given difference equation is stable, unstable or marginally stable with u(k) as step input.(Assume all initial conditions to be zero)

$$y(k+2) + 0.5(k+1) + 0.06y(k) = -0.5u(k)$$

5B. Draw the Nyquist plot of $G(z) = \frac{z}{(z-0.6)(z-0.2)}$; T = 1 s. Determine its closed loop stability.

(5+5)

(4+5+1)

(5+5)
