



VII SEMESTER B.TECH (ELECTRICAL & ELECTRONICS ENGINEERING) END SEMESTER EXAMINATIONS, DECEMBER 2020

APPLICATIONS OF DSP [ELE 4014]

REVISED CREDIT SYSTEM

Time: 3 Hours

Date: 28 December 2020

Max. Marks: 50

Instructions to Candidates:

- ❖ Answer **ALL** the questions.
- ❖ Missing data may be suitably assumed.

1A. What is an eigen function? Mention the eigen function for 2D discrete space LSI systems and also prove it. (02)

1B. State and prove the continuous space Fourier transform of the rotated and translated image $f(A\bar{x} + \bar{b})$, where A is a (2×2) rotation matrix, b is the translation vector, and x is the argument vector of the function f in 2D. (04)

1C. Perform the linear convolution between the following sequences:

$$f(x, y) = \begin{bmatrix} \underline{1} & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}; h(x, y) = \begin{bmatrix} \underline{1} & 1 \\ 1 & 1 \end{bmatrix}. \quad \text{--- : sample at location } (0, 0). \quad (04)$$

2A. Filter the following (5×5) 3-bit image using a (3×3) neighborhood weighted averaging method. Assume the mirror boundary conditions on the boundary of the image.

1	2	3	0	2
4	2	5	2	1
1	2	6	5	3
2	4	6	5	7
1	2	3	4	5

(04)

2B. What is histogram of an image? How do you achieve histogram equalization? (02)

2C. Analyze a (3×3) Sobel filter in the frequency domain and prove that it performs smoothing before detecting edges (Hint: use separability of the Sobel kernel and apply FT). (04)

3A. Derive an expression for the 2D Laplacian operator. Extend it to derive an expression for 2D Laplacian-of-Gaussian (LoG). Assume a unit valued, zero mean, and constant variance Gaussian. Draw waveforms for the Gaussian and its first and second derivatives. (04)

3B. Identify the salt and pepper noise location in the 8-bit image given below:

124	122	133	125	132	000
000	255	124	000	126	123
255	121	132	131	128	255

Perform (3×3) weighted median filtering on the image assuming pixel replication on the boundary of the image. (03)

3C. Explain the scaling, translation, and shearing operations on a shape of interest with relevant diagrams and transformation equations in 2D. (03)

4A. With relevant equations explain Otsu's multi-thresholding algorithm. (02)

4B. What do you understand by 'noise' in image processing? Explain any three noise models. (03)

4C. What is active contour-based segmentation? Explain the shape-template design and mathematical modeling of the cost function optimization of the elliptical shape template. (05)

5A. What is normalized cross-correlation? Prove that it is same as cosine similarity measure. (02)

5B. Explain the DCT-based image compression method. Also, derive expressions for 1D-DCT using DFTs. (04)

5C. Perform the hit-or-miss operation using the structuring elements B_1 and B_2 in Fig. (5B1) on the image given in Fig. (5B2).

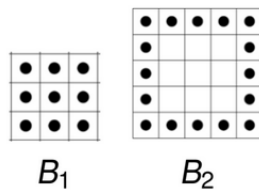


Fig. (5B1)

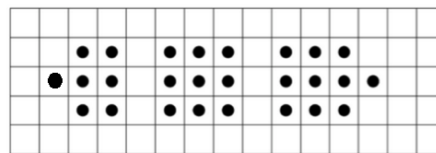


Fig. (5B2)

(04)