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MANIPAL INSTITUTE OF TECHNOLOGY
 (A constituent unit of MAHE, Manipal 576104)

VII SEM B.Tech (BME) DEGREE END-SEMESTER EXAMINATIONS, DEC. 2020.

SUBJECT: ADVANCED IMAGE PROCESSING (BME 4102)
(REVISED CREDIT SYSTEM)

Wednesday, 23rd December 2020, 2 to 5 PM

TIME: 3 HOURS

MAX. MARKS: 50

Instructions to Candidates:

1. Answer ALL the questions.
2. Read all the questions carefully, and answer adequately – but, to the point.

1. (a) It is desired to filter a 2D image of size 250×475, by the unit sample response $h(m,n)$ of size 51×51. A student is asked to implement the filtering operation by using a *Radix-2* FFT algorithm. Write the block diagram describing the precise steps in implementing the filtering operation. Calculate the values of all the parameters involved. (3)

(b) Assume a continuous image, whose gray level is represented by the random variable (RV) X , whose probability density function is given by the expression:

$$f_X(x) = \frac{g_X(x)}{\int g_X(x)dx}, \quad \text{where: } g_X(x) = \begin{cases} \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{(x-6)^2}{2\sigma^2}} - \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{(5.5)^2}{2\sigma^2}}, & x \in [5.5, 6.5] \\ 0, & \text{otherwise} \end{cases} \quad (2)$$

Let Y be the RV representing the probability density function of the *histogram-equalized version* of the original image.

Sketch the cumulative distribution function (*cdf*) associated with the RV Y . Justify your answer.

(c) (i) Perform histogram equalization of the image shown in the accompanying figure (Fig. 1).

Sketch the output image, and its histogram.

9	1	11	11	11	11	11	7
12	12	11	11	11	11	11	11
12	12	11	11	11	11	11	11
12	12	11	11	11	11	11	11
12	12	11	11	11	11	11	11
12	12	11	11	11	11	11	11
12	12	12	12	12	12	12	11
12	12	12	12	12	12	12	12

Figure 1

(ii) Compare the *cdf* with the *cdf* you have sketched in response to Q. 1(b); write your observations and comments. (2)

2. (a) Given the information that the DCT matrix C is orthonormal, prove that C is merely a *rotating transform*. (2)
- (b) (i) Develop from the fundamentals, the convolution-mask (matrix) for computing the Laplacian of an image. (3)
- (ii) How would you use the mask to get the edge-points in the image? (1)
- (iii) Explain as to why, the step in (ii) would not be sufficient to get an image with robust edges. (2)
- What would you do – to make the method robust (explain clearly, with mathematical details where ever necessary). (1)
- (c) You are given a vertical edge-detector mask. Consider an image with edges oriented at 30 degrees. How would you use the given mask for detecting edges in the given image. (2)

3. (a) Write a *pseudo-code* for detecting the presence of vertical lines in an image, by the Hough transform technique. (3)
- (b) (i) Let $\mu_{p,q}$ be the central moments of a function (object) $f(x,y)$. Consider another function $g(x,y)$, which is a rotated version of $f(x,y)$ (let us say, by 25 degrees). How would you compute the angle between the two objects, using their central moments? (2)

(ii) Compute the values of $\mu_{p,q}, \forall p \ \& \ q \ (p+q \leq 3)$ associated with the following objects, respectively:

* a square object extending from -1 to $+1$ along either of the axes; the intensity of the object within the square boundary is 1. (3 Marks)

* the object shown in the accompanying figure (Fig. 2); the gray-level within the object-boundary uniform, with a cluae of 6, and the intensity elsewhere ('background-') is 0. (2 marks)

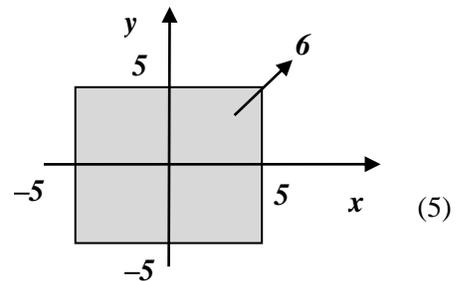


Figure 2

4. (a) Write a *pseudo-code* to implement the rotation of an object, in an image of size 511X511, clockwise by 36 degrees, with respect to its *centroid, c*. (3)

- (b) Sketch the opening and closing of the object shown in Fig. 3 (a), by the structuring element in Fig. 3(b). All the intermediate results must be sketched with clarity and geometric details.

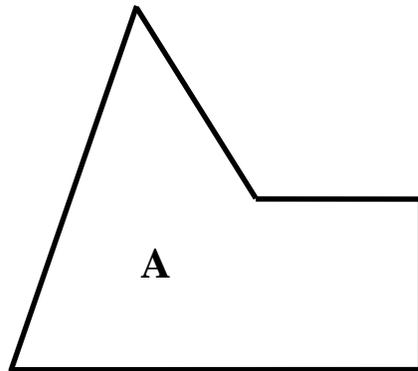


Figure 3(a)

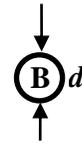


Figure 3(b)

(4)

- (c) Find the number of objects ('blob's) in the figure given in the following (Fig. 4), using the principles of connected component labeling, based on (i) 8 neighborhood, (ii) 4-neighborhood, and (iii) d -neighborhood. Mark the neighborhoods/neighbor-index and/or equivalence-tables, if any, in the all the three cases, to justify your answer.

0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	1	0	0
1	0	0	0	1	0	1	0
0	1	0	1	0	0	0	1
0	0	1	0	0	0	1	0
0	0	0	0	0	1	0	0
0	0	0	0	0	0	0	0

Figure 4

(3)

5. (a) Explain the RGB- and CMYK- colour models. (2)
- (b) (i) How would you justify colour-pixel-classification to enable the segmentation of specific regions of importance, on the wound-bed?

Write down the steps in the procedure for classifying the pixels on a wound-bed, towards assessing the condition of the wound. (5)

With appropriate expressions/figures, justify clearly, the distance-measure used in the process.

(ii) In the context of *digital TB screening* involving analyzing the digital images of ZN-stained sputum smears, discussed in the class, is the use of *proximity-test algorithm* sufficient to classify a beaded bacillus from a clump? If so, explain how? If not, explain the reason, and indicate a solution. Clear answers are paramount to the marks you wish to earn. (3)