

VI SEMESTER B.TECH (BIOTECHNOLOGY) END SEMESTER EXAMINATION, 17 May 2022

SUBJECT: Bioprocess Control & Instrumentation (BIO 3252)

REVISED CREDIT SYSTEM ANSWER ALL QUESTIONS

TIME: 3 HOURS

MAX. MARKS: 50

Q. NO		MARKS	CO	BTL
1A	What are the main control objectives of Bioprocess plant.	2	1	1
1B	What are the external disturbances in a stirred tank heater and how will you design (all possible ways) a control system to suppress the external disturbances.	5	1	4
1C	Briefly explain the response of a stable and unstable process with neat diagram.	3	1	2
2A	Label important common measurements and controls in a bioreactor.	2	2	1
2B	What are the basic requirements of a sensor or transducer and briefly explain them	4	2	1
2C	Consider the two stirred tank heaters shown in Figure. F_1, T_1 F_2, T_2 F_3, T_4 F_2, T_2 F_3, T_4 F_4, T_4 F_5, T_4	4	2	5
3 A	Using partial fraction expansion, find x(t) for (a) $X(s) = \frac{S(S+1)}{(S+2)(S+3)(S+4)}$ (b) $X(s) = \frac{(S+1)}{(S+2)(S+3)(S^2+4)}$	5	3	6
3B	A heated process is used to heat the liquid in the tank with first order dynamics, that is, the transfer function relating changes in temperature T to changes in the heater input power level P is	3	3	6

	$\frac{T(s)}{P(s)} = \frac{K}{\tau s + 1}$ Where K has units [°C/Kw] and τ has units (minutes). The process is at steady state when an engineer changes the power input stepwise from 1 to 1.5 Kw, the following have been observed: (a) The process temperature initially is 80 °C. (b) Four minutes after changing the power input, the temperature is 230 °C. (c) Thirty minutes later (steady state) the temperature is 280 °C. Determine the values of K and τ in the process transfer function			
3C	What are the 3 categories, where the second order or higher dynamics can arise from several physical situations.	2	3	1
4 A	Briefly explain the direct acting and reverse acting control valve function.	2	2	3
4B	Consider the block diagram shown in the following figure. simplify (reduce) this block diagram using the block diagram reduction rules. $R(s) + C_1 + C_2 + C_3 + C_5 $	4	4	5
4C	The setpoint of the control system in figure given a step change of 0.1 unit. Determine $\frac{Y_{sp}}{(s+1)(2s+1)} \xrightarrow{Y}$ (a) offset, (b) overshoot, (c) decay ratio and (d) period of oscillation	4	4	6
5A	Determine the range of K that stabilizes the below closed loop system $Y_{sp} + \underbrace{K \rightarrow f}_{(s+2)(s+3)} + \underbrace{\frac{1}{s}}_{s} + \underbrace{Y}_{sp}$	4	4	5

5B	Consider a process with the transfer function: $G_p(s) = \frac{1}{(s^4 + 10s^3 + 36s^2 + 56s + 32)}$	3	5	6		
	If a PI Controller is used to control this process, determine the value of the integral time τ_I and K _c using the Ziegler-Nichols closed loop tuning method.					
5c	Briefly explain the trouble shooting of common control loops.	3	5	2		
CO: Course Outcome; BLOOM TAXONOMY LEVEL: 1-Remember, 2-Understand, 3-Apply, 4-Analyze, 5-Evaluate, 6-Create						