Exam Date & Time: 19-Dec-2022 (02:30 PM - 05:30 PM)



MANIPAL ACADEMY OF HIGHER EDUCATION

THIRD SEMESTER B.TECH END SEMESTER EXAMINATIONS, DEC 2022 SIGNALS AND SYSTEMS [BME 2155]

Marks: 50

Answer all the questions.

Instructions to Candidates: Answer ALL questions Missing data may be suitably assumed

1) Consider a discrete-time sequence

$$x(n) = \{1, 2, 2, 1, 1, 2\}$$

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Determine graphically, x(2n) - x(-n) + x(-n+1).

B) A sequence x(n) has a zero-phase DTFT X(w) as sketched in the figure below. Use a suitable property of DTFT and sketch the DTFT of the sequence $x(n)e^{-jn\frac{\pi}{s}}$.



Duration: 180 mins.

(3)

(2)

C)

Consider the LSI system built by the interconnections of sub-systems with impulse responses $h_1[n] = u[n]$, $h_2[n] = -u[n-1]$, $h_3[n] = u[n-1]$ and $h_4[n] = \delta[n]$ as shown in the figure below. Determine the response y[n] of the system for a given input $x[n] = \delta[n]$.



3)

A discrete-time signal x(n) is given by:

(3)

(5)



Determine graphically each of the following versions of the signal.

(i)
$$x(n+2)u(2-n)$$

(ii) $x(n-1)\delta(n-3)$
(j) Using DTFT, Solve $y(n) = x(n) * h(n)$
where
 $x(n) = \{1, 1, 1, 1, -1, -1\}$ and
 $h(n) = \delta(n-2) - \delta(n-4)$.
(c) Calculate the inverse Z-transform of
 $X(z) = \frac{z}{zz^2 - 4z + 1}$
for the following ROCs:
 $|z| > 1$
(i)
 $|z| < \frac{1}{3}$
(ii)
 $\frac{1}{3} < |z| < 1$
(iii)
A continuous-time signal $x(t)$ is described by
(3)
A) $x(t) = 6\cos(50\pi t) + 3\sin(20\pi t) - 3\cos(100\pi t)$. Determine the following:
(i) minimum sampling frequency required to sample the signal.
(i) corresponding discrete-time sequence.

B) A discrete-time signal is given by

$$x(n) = \{-3, 4, 2, 0, 1, -1, 3, -2\}$$

Determine graphically each of the following versions of the signal using the precedence rule:

(i)
$$x(-n-1)$$

(ii) $x(1-n)$

(3)

| | a) Non-linear Time-variant Non-causal system | |
|----|--|--|
| | | |
| | b) Non-linear Time-invariant Non-causal system | |
| | c) Linear Time-invariant Causal system | |
| | d) Linear Time-variant Causal system | |
| | Consider an LSI system described by the difference equation, $y(n) = x(n) - x(n-1)$. | (4) |
| A) | (i) Determine the frequency response $H(w)$ and the impulse response $h(n)$ of the system. | |
| | (ii) Sketch the magnitude response $ H(w) $ over $-\pi \le w \le +\pi$ and identify the system. | |
| B) | Calculate the response $y(n)$ of the LSI system whose impulse response $h(n) = \begin{cases} 1 & -2 \le n \le 2 \\ 0 & Otherwise \end{cases}$ | (4) |
| | and the input | |
| | $x(n) = \begin{cases} \frac{n}{3} & 0 \le n \le 6\\ 0 & Otherwise \end{cases}$ | |
| C) | Determine the Z-transform of the series that has the Fourier transform $X(w) = 1 + \cos(w)$ | (2) |
| | Analyze and find out whether the following LSI systems are Causal? Stable? (Justify your answers). | (3) |
| A) | h(n) = 2u(n) - 2u(n-1) | |
| | $h(n) = 2^n u(-n)$ | |
| B) | Determine the Z-transform $X(z)$ and sketch the pole-zero plot with the ROC for each of the following sequences: | (4) |
| | _(i) $x(n) = \left(\frac{1}{2}\right)^n u(n) + \left(\frac{1}{3}\right)^n u(n)$ | |
| | $x(n) = \left(\frac{1}{3}\right)^n u(n) + \left(\frac{1}{2}\right)^n u(-n-1)$ | |
| C) | Show that the LSI system described by the difference equation, $y(n) = x(n) + x(n-1)$, represents a low pass filter. | (3) |
| | A) 3) C) A) 3) | b) Non-linear Time-invariant Non-causal system c) Linear Time-invariant Causal system d) Linear Time-invariant Causal system Consider an LSI system described by the difference equation, $y(n) = x(n) - x(n-1)$. (i) Determine the frequency response $H(w)$ and the impulse response $h(n)$ of the system. (ii) Sketch the magnitude response $ H(w) $ over $-\pi \le w \le +\pi$ and identify the system. Calculate the response $y(n)$ of the LSI system whose impulse response $h(n) = \begin{cases} 1 & -2 \le n \le 2 \\ 0 & -2 \ nterwise$ and the input $x(n) = \begin{cases} \frac{\pi}{0} & 0 \le n \le 6 \\ 0 & 0 \ therwise$ Determine the Z-transform of the series that has the Fourier transform $\chi'(w) = 1 + \cos(w)$. Analyze and find out whether the following LSI systems are Causal? Stable? (Justity your answers). h(n) = 2u(n) - 2u(n-1) (i) Determine the Z-transform $\chi'(z)$ and sketch the pole-zero plot with the ROC for each of the following sequences: $u(nx(n) = (\frac{1}{2})^n u(n) + (\frac{1}{2})^n u(n)$ $x(n) = (\frac{1}{2})^n u(n) + (\frac{1}{2})^n u(-n-1)$ (ii) C) Show that the LSI system described by the difference equation, $y(n) = x(n) + x(n-1)$, represents a low pass filter. |

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