

Question Paper

Exam Date & Time: 28-Nov-2022 (09:00 AM - 12:00 PM)



MANIPAL ACADEMY OF HIGHER EDUCATION

SEVENTH SEMESTER B.TECH END SEMESTER EXAMINATIONS, ICE DEPARTMENT, NOV 2022

Robust Control [ICE 4053]

Marks: 50

Duration: 180 mins.

A

Answer all the questions.

Instructions to Candidates: Missing data may be suitably assumed

1) Find the general unity negative feedback control system block diagram shown in Fig.1A find

(2)

A)

$$(i) \frac{y(s)}{d(s)} \quad (ii) \frac{e(s)}{r(s)}$$

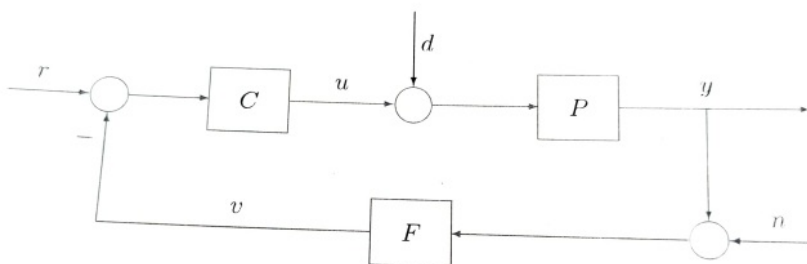


Fig.1A Control system block diagram

[CO1,PO1,PO2,BL1,BL2]

B) Write the steps for Euclid's Algorithm and prove the Bezout- Identity.

(3)

[CO2,PO2,PO3,BL2,BL3]

C) Consider a plant

(5)

$$P(s) = \frac{(s - 1)}{s^2 + 1}$$

$$1 - (s - 2)$$

$$(s - 2)^2$$

and a controller

$$C(s) = \frac{X + MQ}{Y - NQ}$$

, find X, Y, M & N. Also, find 'Q' under the condition Y=1, reference input signal R=1 and disturbance d=0.

[CO3,PO4,PO5,BL4,BL5]

- 2) Using Parity Interlacing property comment on the compensator stability for the following transfer functions

(2)

A)

$$(i) P(s) = \frac{s^2 - 3s + 2}{s^2 - 3.9s + 2.7} \quad (ii) P(s) = \frac{s}{(s - 1)^3}$$

[CO4,PO3,PO4,PO5,BL4,BL5]

- B) Explain the properties of linear fractional transformation with its necessary equations. Also, write the state and output equations. [CO3,PO1,PO2,BL2,BL3] (3)

- C) Briefly discuss on the Robust stability and Robust performance graphically using disc analysis. Also, summarize various perturbations and its condition. (5)

[CO4,PO1,PO2,BL2,BL4]

- 3) Illustrate the loop shaping techniques by summarizing the condition for weighting function W1 and loop transfer function L. [CO3,PO1,PO2,BL2,BL3] (2)

A)

- B) Derive the weighting functions of W1 and W2 for advanced loop shaping techniques. (3)

[CO5,PO3,PO4,PO5,BL3,BL4]

- C) Explain the controller design procedures for the P inverse stable and unstable processes with the help of filter J and improper transfer function Q [CO5,PO4,PO5,BL5,BL6] (5)

- 4) Find $F_l(P, K)$ for the general unity feedback control with r, n and d signals with necessary linear fractional transformation diagram. [CO4,CO5,PO5,PO6,BL4,BL5] (2)

A)

- B) Write the partition matrix structures for the following (3)

i. Full information problem.

ii. Disturbance feed-forward problem.

iii. Output estimation problem. [CO2,CO3,PO1,PO2,BL1,BL2]

- C) Using a state space method obtain the coprime factorization of the plant (5)

$$P(s) = \frac{s - 1}{s(s - 2)}, \text{ given } F = [-1 \ -3] \text{ \& } L = [-4 \ -9]^{-1}$$

. Verify using Bezout's Identity.

[CO5,PO4,PO5,BL3,BL4,BL5]

- 5) Write the improper transfer function Q formula with the condition involving RHS zero and gamma. [CO4,PO5,PO6,BL3] (2)
- A)
- B) Address the model mismatch problem using gamma. [CO3,CO4,PO3,PO4,BL2] (3)
- C) Derive for the solution for the modified problem involves transforming it into the model mismatch problem. [CO5,PO5,PO6,PO5,BL5] (5)

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