

## FOURTH SEMESTER B.TECH. (AERONAUTICAL ENGINEERING) END SEMESTER EXAMINATIONS, MAY 2024

## **LINEAR CONTROL THEORY [AAE 2223]**

REVISED CREDIT SYSTEM

Time: 3 Hours Date: 26 JUNE 2024 Max. Marks: 50

## **Instructions to Candidates:**

- Answer ALL the questions.
- Missing data may be suitably assumed.

Q.NO	Questions	Marks	СО	BTL
1A.	Determine the Trasfer Fucntion $X_1(s)/F(s)$ and $X_2(s)/F(s)$ for the system shown in the figure below,		C01	L3
	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	(04)		
1B.	Obtain the Trasfer Function of the electrical network shown in the figure below,		CO1	L2
	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	(03)		
1C.	An automatic washing machine is an example of a closed-loop control system. The machine needs to control the water level, temperature, and agitation speed during the wash cycle.		CO2	L2
	a. Identify the controlled variables, manipulated variables, and disturbances in this system.			
	b. Draw a detailed block diagram representing the control loops involved in the washing machine.			
		(03)		

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	c. Discuss how the feedback mechanism ensures proper washing performance and energy efficiency.			
2A.	For the system represented by the block diagram shown in the figure below, Evaluate the close loop transfer function when the R (input) is at Station-I	(04)	CO2	L3
2B.	For the Signal Flow Graph shown in the below figure, obtain the Transfer Function $C(S)/R(S)$ , $G_{3}$ $G_{4}$ $G_{3}$ $G_{4}$ $G_{5}$ $G_{7}$ $G_{1}$ $G_{3}$ $G_{4}$ $G_{3}$ $G_{4}$ $G_{3}$ $G_{4}$ $G_{5}$ $G_{7}$ $G_{8}$ $G_{9}$ $G_{1}$ $G_{1}$ $G_{1}$ $G_{2}$ $G_{3}$ $G_{4}$ $G_{3}$ $G_{4}$ $G_{5}$ $G_{7}$ $G_{8}$ $G_{9}$ $G_{1}$ $G_{1}$ $G_{2}$ $G_{3}$ $G_{4}$ $G_{5}$ $G_{7}$ $G_{8}$ $G_{9}$ $G_{1}$ $G_{1}$ $G_{1}$ $G_{2}$ $G_{3}$ $G_{1}$ $G_{2}$ $G_{3}$ $G_{4}$ $G_{5}$ $G_{7}$ $G_{8}$ $G_{8}$ $G_{8}$ $G_{8}$ $G_{9}$ $G_{1}$ $G_{1}$ $G_{1}$ $G_{2}$ $G_{3}$ $G_{1}$ $G_{2}$ $G_{3}$ $G_{4}$ $G_{5}$ $G_{8}$ $G_{8$	(04)	CO2	L3
2C.	For the Signal Flow Graph shown in the below figure, obtain the overall Transfer Function using Mason's Gain formula,	(02)	CO2	L3
3A.	Compute the necessary values required to sketch <b>Root Locus Plot</b> for the Open Loop Transfer Function, G(s) H(s)=K/s(s+1)(s+5)	(05)	C04	L4
3B.	Comment on stability for the characteristic equation. $S^5 + S^4 + 2 S^3 + 2 S^2 + 3S + 5$ Using Routh-Hurwitz criteria.	(03)	соз	L3
3C.	Sketch <b>Root Locus Plot</b> in graph sheet for the <b>Q. No (3A)</b> and analyse the stability	(02)	CO4	L4
4A.	Compute the necessary values required to draw <b>Bode Magnitude and Phase Plot</b> for the Open Loop Transfer Function, $G(s) = 40/s(s+2)(s+20)$	(05)	CO4	L4
4B.	Plot the <b>Bode Magnitude Plot and Phase plot</b> for the <b>Q. No. (4A)</b> in Semilog sheet and analyse the Stability.	(03)	CO4	L4
4C.	Draw the approximate <b>Polar plot</b> and <b>Nyquist Plot</b> for the Transfer Function $G(S)=10/s(s+0.01)(s+0.02)$ by observing the Type and Order of the system.	(02)	CO4	L4

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5A.	A unity feedback control system has a open loop transfer $G(S) = \frac{10}{S(S+2)}$ function .		соз	L3
	Find (a) Rise Time (b) Percentage of overshoot (c) Peak Time (d) Settling Time for a step unit of 12 units.	(04)		
5B.	Obtain the state space model for the system having transfer $\frac{Y(S)}{U(S)} = \frac{1}{S^2 + S + 1}$ function,	(04)	CO5	L3
5C.	Find the steady state error when the input is unit ramp signal for type-1 and type-2 system.	(02)	соз	L3

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