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(A constituent unit of MAHE, Manipal)

DEPARTMENT OF MECHATRONICS II SEMESTER M.TECH. (INDUSTRIAL AUTOMATION & ROBOTICS) END SEMESTER EXAMINATIONS, MAY 2024 SUBJECT: ARITIFICAL INTELLGENCE AND EXPERT SYSTEMS [MTE 5002] Date: 05 May 2024

Time: 3 Hours

MAX. MARKS: 50

Instructions to Candidates:

- Answer **ALL** the questions.
- Missing data can be assumed and suitably justified.

Q. No	Question	Μ	CO	PO	LO	BL
1A.	In a credit card fraud detection system, out of 80 fraudulent transactions, the system	5	1	3	2	3
111,	correctly identifies 70 as fraud and misses 5. It correctly classifies 900 non-fraudulent					
	transactions as not fraud, but incorrectly flags 10 as fraud. Illustrate the confusion matrix					
	and calculate the precision, recall, and F1 score of the fraud detection system.					
1R	A man is known to speak truth 3 out of 4 times. He throws a die and reports that it is a	3	1	3	2	4
10,	six. Examine the probability that it is actually a six.					
1C.	Explain how Bayesian networks enhance predictive modeling in machine learning by leveraging conditional independence statements and probabilistic reasoning to represent complex relationships among variables?	2	1	3	1	4
2A.	A Bayesian network is used to model the relationship between a patient's symptoms, medical history, and the likelihood of having a particular disease. The network has three variables:	5	1	1	2	5
	A: The patient's medical history (positive or negative)					
	B: The patient's symptoms (present or not present)					
	C: The likelihood of having the disease (high, medium, or low)					
	The conditional probability table for the network is as follows:					
	P(B=present A=positive, C=high) = 0.9					
	P(B=present A=positive, C=medium) = 0.6					
	P(B=present A=positive, C=low) = 0.3					
	P(B=present A=negative, C=high) = 0.6					
	P(B=present A=negative, C=medium) = 0.3					
	P(B=present A=negative, C=low) = 0.1 P(C=bich A=negitive) = 0.5					
	P(C=mgn A=positive) = 0.3 $P(C=mgn A=positive) = 0.4$					
	P(C=low A=positive) = 0.1					
	P(C=high A=negative) = 0.2					
	P(C=medium A=negative) = 0.5					
	P(C=low A=negative) = 0.3					
	Given this information, Estimate the probability of a patient having a high likelihood of					
	having the disease (C=high) if they have symptoms (B=present).				-	
2B.	You have performed k-means clustering on a dataset containing customer spending data.	3	1	3	2	5
	The dataset consists of features such as annual income and spending score. After abutating the data into k abutars, you want to actimate the ailboutte coefficient for					
	cluster 2 point B2 by evaluating cohesion and separation distance between the clusters					
	cluster 2, point b2 by evaluating concision and separation distance between the clusters.					

· · · · · · · · · · · · · · · · · · ·	Assume that the dataset has been clustered into 3 clusters $(k=3)$ and the cluster labels for						1	1	
	Assume that the dataset has been clustered into 3 clusters (k=3), and the cluster labels for each data point are given under table.								
	Table 1: Cluster labels for the given datapoints								
	Cluster 1	Cluster 2	Cluster 3						
	Point A1: (2,5)	Point B1:(8,3)	Point C1: (6,10)						
	Point A2:(3,4)	Point B2: (9,2)	Point C2: (7,8)						
	Point A3:(4,6)	Point B3: (10,5)	Point C3: (8,9)						
2C.	Consider two data points	$x = \begin{bmatrix} 1 \\ 2 \end{bmatrix}; y = \begin{bmatrix} 2 & 3 \end{bmatrix}$ with	r C, σ and $q = 1$, Estimate	linear, Non	2	1	3	2	4
	homogenous and homoge	nous kernel calculation	in SVM.	. 0	~	-		_	-
3A.	Apply Genetic algorithm	to maximize the value of $\frac{1}{10}$	t the function $f(x) = -x^2$ -	+ $2x$. Given	5	2	3	2	5
	0.4, 0.15, 0.7 and 0.9. Se best value for a function a	lect the crossover betw fter two iterations.	een first and fifth digits. De	etermine the					
3B.	Discuss the applications of	of Genetic Algorithms (GAs) in the fields of enginee	ering design	3	2	1	1	5
	and computer-aided mole using GAs in these areas addressed using this appro-	ccular design. Discuss t s, and provide example bach.	the challenges and potential es of specific problems that	benefits of have been					
3C.	Explain the concept of examine it affects the bala	"inertia weight" in Parance between exploration	rticle Swarm Optimization on and exploitation in the alg	(PSO) and gorithm.	2	2	1	1	4
4A.	Consider a neural networ The input layer has 3 neural networ The input layer has 3 neural neurons. The activation fur- function. Suppose we have a training corresponding target output The weights and biases of 1. Input to Hidden $W_{ih} = \begin{bmatrix} 0.1 & 0.2 \\ 0.2 & 0.3 \\ 0.3 & 0.4 \end{bmatrix}$ 3. Hidden layer bia $\boldsymbol{b}_{h} = \begin{bmatrix} 0.1 \\ 0.2 \\ 0.3 \\ 0.4 \end{bmatrix}$ 3. Hidden to output $\boldsymbol{W}_{ho} = \begin{bmatrix} 0.5 & 0. \\ 0.6 & 0. \\ 0.7 & 0. \\ 0.8 & 0. \end{bmatrix}$ 4. Output Layer W $\boldsymbol{b}_{o} = \begin{bmatrix} 0.5 \\ 0.6 \end{bmatrix}$ The network uses the mean Perform one step of back using stochastic gradient of the state	htte between explorate k with one input layer, rons, the hidden layer h inction used in both the ng example where the i ut is [0.4, 0.7]. The neural network are Layer Weights: 2 0.3 0.4 0.4 0.5 0.5 0.6 ses: 1t layer weights: 6 7 8 9 9 //eights:	loss function for training. e the weights and biases of the same and biases of the same set of 0.1.	the network	5	3	1	2	5
4B.	A data scientist working for a cybersecurity firm, tasked with developing a machine learning model to detect malicious network traffic and prevent cyberattacks. After considering various algorithms, you decide to use Random Forest due to its ability to handle high-dimensional data and provide robust classification performance. Anticipate the drawbacks occurred as you deploy and evaluate the Random Forest model in a real-world cybersecurity environment.					3	1	2	6
4C.	Imagine, you're developi banking system. The neur (representing transaction neuron indicating whethe applicability of backprop network, considering fa computational efficiency.	ng a neural network for al network architecture features), one hidden r the transaction is frau- pagation and reinforce ctors such as data ar	or detecting fraudulent trans- includes one input layer with layer with 30 neurons, and dulent or not. Compare and ement learning in training vailability, feedback mech-	actions in a 50 neurons one output contrast the this neural anism, and	2	3	1	2	5

5A.	A robot is navigating through a grid-based environment to reach its destination. The grid consists of obstacles and open spaces, and the robot needs to make decisions at each grid cell to determine its next move. You decide to use a decision tree classifier with the Gini index as the splitting criterion to assist the robot in path planning. Given a sample dataset containing the following features and labels: Evaluate the Gini index for each feature and determine the optimal feature and split point for the root node of the decision tree based on the provided dataset: Pictorially represent the final decision tree for the given dataset under table 1.						5	4	3	2	5
	Grid Cell	Obstacle	Terrain Type	Visibility	Action						
	1	Clear path	Open Space	Clear	Move						
		F	• F • • • F • • • •		Forward						
	2	Solid Rocks	Rough Terrain	Partially Obscured	Turn Left						
	3	Water bodies	Obstacle	Obscured	Stop						
	4	Clear path	Open Space	Clear	Move						
					Forward						
	5	Solid rock	Rough Terrain	Partially Obscured	Turn						
	Right										
5B.	In the field of healthcare robotics, you've been tasked with designing a robotic system to assist elderly individuals with daily living activities in nursing homes. The robotic system is intended to provide support with tasks such as medication reminders, mobility assistance, and social interaction. Your goal is to develop a user-friendly and effective robotic solution that improves the quality of life for elderly residents while addressing their unique needs and preferences. Formulate the design procedures of robotic systems to be incorporated in a healthcare robotics system to enhance the quality of life for elderly individuals in nursing homes, considering factors such as user acceptance, autonomy, safety, and ethical considerations?					n to em lity ive ing are es, ns?	3	5	5	7	6
5C.	In a swarm robotics simulation, a neural network controller is trained using a genetic algorithm (GA). The genetic algorithm initializes a population of 50 neural network controllers with random weights and biases. Each controller is evaluated based on its performance in completing a specific task, and the top 20 controllers are selected for crossover and mutation. If the crossover rate is 0.7 and the mutation rate is 0.1, determine the number of offspring produced in the next generation.						2	5	3	17	5